## Sliding Door Operator EM PSL150-T



Installation and Service Manual Original instructions
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## CONTENTS - Original instructions

1 Revision ..... 6
2 Instructions for safe operation ..... 7
3 Important information ..... 8
3.1 Intended use ..... 8
3.2 Safety precautions ..... 8
3.3 Electronic equipment reception interference ..... 8
3.4 Environmental requirements ..... 9
1 About this manual ..... 10
1.1 Software releases with included software versions ..... 10
5 Technical specification ..... 11
5.1 Door weight in relation to performance level ..... 12
5.2 Classification to DIN 18650-1 ..... 13
6 Design and function description ..... 14
6.1 Design ..... 14
6.2 Function ..... 14
6.3 Safety functions integrated in the operator ..... 14
6.4 Microprocessor for precise control ..... 14
6.5 Emergency escape ..... 14
7 Models ..... 15
8 Part identification ..... 17
9 Space required ..... 18
10 Pre-installation ..... 19
10.1 General tips/Safety concerns ..... 19
11 Mechanical installation ..... 20
11.1 Checking ..... 20
11.2 Installation examples to consider during installation ..... 22
11.3 Installing/removing the cover, standard cover lock ..... 24
11.4 Installing/removing the cover, optional cover lock ..... 26
11.5 Installing the door adapter on top of the door leaf(frame doors by others) ..... 28
11.6 Installation of support beam ..... 29
11.7 Mount the secondary track onto the slow moving door ..... 31
11.8 Installing the door holders on the door adapter (frame doors by others) ..... 32
11.8.1 Slow moving door ..... 32
11.8.2 Fast moving door ..... 32
11.9 Hanging and mounting the slow moving door leaves ..... 35
11.10 Height adjust the slow moving doors ..... 36
11.11 Installation of telescopic wire ..... 37
11.12 Install the fast moving doors ..... 40
11.13 Installation of Entrematic Nordic floor guides (frame doors by others) ..... 41
11.14 Depth adjustment of the door leaves ..... 43
11.15 Connect the fast moving door to the slow moving door ..... 44
11.16 Installation of components and electrical wiring ..... 48
11.17 Installation of tension wheel assembly ..... 50
11.18 Placement of the transmission bracket ..... 51
11.19 Attachment of tooth belt fitting ..... 52
11.20 Checking and adjusting the belt tension ..... 53
11.21 Bi-parting operators ..... 54
11.22 Mount the doorstop ..... 55
11.23 Route the cables and attach the plastic cable holders, see illustrations below ..... 57
11.24 Attachment of slack reducer ..... 58
11.25 Attachment of product label ..... 59
12 Electrical connections ..... 60
12.1 Mains connection ..... 60
12.2 Electrical units ..... 61
12.2.1 Power supply unit (PSU 75/PSU 150) ..... 61
12.2.2 Drive unit (HDD/DD) ..... 61
12.2.3 Main control unit (MCU/MCU-ER) ..... 62
12.2.4 Additional electronic units can be connected for extra functionality ..... 63
12.2.4.1 Battery unit 12 V (EEU 12) ..... 63
12.2.4.2 Battery unit 24 V (EEU 24) ..... 63
12.2.4.3 I/O unit (IOU) ..... 64
12.2.5 Connection of electrical units ..... 65
12.3 Connection of activation and safety units ..... 67
12.4 Connection of presence activation units ..... 68
12.5 Connection of accessories ..... 69
13 Start-Up ..... 70
13.1 Adjustments and selection of special operating functions ..... 71
13.2 The Learn function can be one of three different types ..... 73
13.3 Display test and configuring of parameters ..... 74
13.4 Status indication on the display ..... 75
13.5 Configuration parameters (sorted after functionality) ..... 76
13.6 Description of parameters ..... 81
14 Signage ..... 97
15 Accessories ..... 98
15.1 Interconnection of operators ..... 98
15.1.1 Interconnection cable ..... 98
15.1.2 Hardware configuration for interconnection ..... 99
15.1.3 Parameter configuration for interconnection ..... 99
15.2 Interlock ..... 99
15.3 Synchronization ..... 100
15.4 Operation mode selectors (OMS) ..... 101
15.4.1 Types ..... 101
15.4.2 Operation mode selector (OMS) functionality ..... 102
15.5 Replacement of secondary track ..... 105
15.5.1 Shortening of secondary track ..... 105
15.5.2 Shortening the bar ..... 105
15.5.3 Shortening the $L$-profile ..... 105
15.5.4 Shortening the shim ..... 105
15.5.5 Shortening the tube ..... 106
15.5.6 Shortening and creating new holes in the secondary track ..... 106
15.5.7 Assemble the secondary track ..... 107
15.6 Lock ..... 110
15.6.1 Mounting the lock ..... 110
15.7 Cover ..... 113
15.8 Motion sensor and presence sensors ..... 113
15.9 Manual Opening Lock device, MOLD ..... 113
15.10 Limit switch kit, LSK ..... 115
15.11 Lock indication switch, LIS ..... 115
15.12 Locked door indicator, LDI ..... 116
15.13 Quick connectors ..... 117
15.13.1 $2 \times 10$ to $1 \times 10$ converter ..... 117
15.13.2 8 to 10 converter ..... 117
15.14 Cover latch, alternative ..... 118
15.15 Electrical emergency unit with batteries ..... 118
15.16 Electrical emergency unit with batteries and two motors ..... 118
15.17 Emergency closing with repeated closing ..... 118
15.18 Break-out unit PSB ..... 119
15.19 Convenience battery UPS ..... 119
15.20 External error indication ..... 119
15.21 Key switches (flush and/or surface mounted) ..... 119
15.22 Push button ..... 119
15.23 Upgrades ..... 119
15.24 Open / Close function ..... 120
15.25 Fire alarm connection ..... 120
15.26 Nurse function ..... 120
15.27 Remote Exit mode ..... 120
15.28 Emergency open impulse ..... 120
16 Troubleshooting ..... 121
16.1 After remedy or replacement the operator has to be checked as follows: ..... 126
17 Service/Maintenance ..... 127
17.1 Service ..... 128

## 1 Revision

Following pages have been revised:

| Page | Revision $\mathbf{3 . 0} \boldsymbol{\mathbf { 4 . 0 }}$ |
| :--- | :--- |
|  | Updated manual to software version 5.0. |
| 31 | Improved Mount the secondary track onto the slow moving door. |
| 87 | Changed parameter 49. |
| 87 | Changed parameter 4A. |
| 87 | Changed parameter 50. |
| 105 | Improved Replacement of secondary track. |
| 119 | Added requirements in Escape route according to EN16005 and DIN 18650. |
| 125 | Added error E6:47. |

## 2 Instructions for safe operation



- Failure to observe the information in this manual may result in personal injury or damage to equipment.
- To reduce the risk of injury of persons - use this operator only with pedestrian doors.
- Do not use the equipment if repair or adjustment is necessary.
- Disconnect supply when cleaning or other maintenance is to be carried out.
- The operator can be used by children over 8 years of age ifthey have been instructed by a person in charge of their safety.
- The operator can be used by children 8 years of age or younger if they are supervised by a person responsible for their safety.
- The operator can be used by persons with impaired physical, sensory or mental capacity if they have been instructed by a person in charge of their safety.
- Cleaning and user maintenance shall not be made by children.
- Do not let anyone climb on or play with the door or the fixed/remote controls.
- In all instances, where work is being done, the area is to be secured from pedestrian traffic, and the power removed to prevent injury.
- Installer must properly ground door package! Improper grounding can lead to risk of personal injury.
- The mains connection must remain isolated until the wiring is completed. Then connect to the supply unit.
- The doorset can be operated automatically by sensors or manually by activators.


## 3 Important information

### 3.1 Intended use

The EM PSL150-T is an automatic sliding door operator developed to facilitate entrances to buildings and within buildings.
The EM PSL150-T is designed to be surface-mounted to the wall or a beam. It is easy to install for both new construction and retrofit application, and it can be adapted to a wide range of door requirements. It is to be installed indoors where it is suitable for almost all types of external and internal sliding doors.
The door is designed to offer continuous use, a high degree of safety and maximum lifetime. The system is self-adjusting to the effects caused by normal variations in the weather conditions and to minor friction changes caused by e.g. dust and dirt.

In emergency situations the doorset is opened and remains open automatically. It may also be equipped with break-out function, in which case the door leaf is pushed manually open in the escape direction.
Dual batteries and motors are used in escape routes as indicated in associated certificates. See "Electrical emergency unit with batteries" on page 118 and "Electrical emergency unit with batteries and two motors" on page 118. For manual break-out see "Break-out unit PSB" on page 119.
This manual contains the necessary details and instructions for the installation, maintenance and service of the Sliding Door Operator EM PSL150-T.
For use see User manual 1016696.
Save these instructions for future reference.

## $3.2 \quad$ Safety precautions

Be sure to complete a risk assessment and site acceptance test before taking the door into operation.
To avoid bodily injury, material damage and malfunction of the product, the instructions contained in this manual must be strictly observed during installation, adjustment, repairs and service etc. Training is needed to carry out these tasks safely. Only Entrematic Nordic-trained technicians should be allowed to carry out these operations.

### 3.3 Electronic equipment reception interference

The equipment may generate and use radio frequency energy and if not installed and used properly, it may cause interference to radio, television reception or other radio frequency type systems.

If other equipment does not fully comply with immunity requirements interference may occur.
There is no guarantee that interference will not occur in a particular installation. If this equipment does cause interference to radio or television reception, which can be determined by turning the equipment off and on, the user is encouraged to try to correct the interference by one or more of the following measures:

- Re-orient the receiving antenna.
- Relocate the receiver with respect to the equipment.
- Move the receiver away from the equipment.
- Plug the receiver into a different outlet so that equipment and receiver are on different branch circuits.
- Check that protective earth (PE) is connected.

If necessary, the user should consult the dealer or an experienced electronics technician for additional suggestions.

### 3.4 Environmental requirements

Entrematic Nordic products are equipped with electronics and may also be equipped with batteries containing materials which are hazardous to the environment. Disconnect power before removing electronics and battery and make sure it is disposed of properly according to local regulations (how and where) as was done with the packaging material.

## 1 About this manual

This manual describes functions of the EM PSL150-T Sliding Door Operator and for software release 5.0.

## 1.1 <br> Software releases with included software versions



## 5 Technical specification

| Manufacturer: | Entrematic Nordic AB |
| :---: | :---: |
| Address: | Lodjursgatan 10, SE-261 44 Landskrona, Sweden |
| Type: | EM PSL150-T |
| Mains power supply: | $100 \mathrm{~V} \mathrm{AC}-10 \%$ to $240 \mathrm{~V} \mathrm{AC}+10 \%, 50 / 60 \mathrm{~Hz}$, fuse 10 AT (building installation) <br> Note! The mains power supply shall be installed with protection and an all-pole mains switch with isolating capability of Category III, at least 3 mm between contacts, shall be installed according to local regulations. These articles are not provided with the door. |
| Power consumption: | Max. 250 W |
| Degree of protection: | IP20 |
| Degree of protection, control actuators: | IP54 |
| Auxiliary voltage: | 24 V DC  <br> High performance 0.64 A <br> Exceptional performance 1 A |
| Recommended max. door weight: | Bi-parting without break-out: <br> EM PSL150-T-2: $80 \mathrm{~kg} /$ leaf <br> Single Slide without break-out: <br> EM PSL150-T-R/L: $80 \mathrm{~kg} /$ leaf <br> For low energy movement: $75 \mathrm{~kg} / \mathrm{leaf}$ |
| Clear opening: | Bi-parting: <br> EM PSL150-T-2: 1720-3000 mm <br> Single Slide: <br> EM PSL150-T-R/L: 900-3000 mm |
| Opening and closing speed: | Variable up to approx. (EM PSL150-T-2): |
| Hold open time: | 0-60 s |
| Ambient temperature: | $-20^{\circ} \mathrm{C}$ to $+50^{\circ} \mathrm{C}$ |
| Relative humidity (non-condensing): | Max. 85\% |
| Operator weight: | 11 to 25 kg , dependent on configuration and clear opening width |
| Approvals: | Third party approvals from established certification organizations valid for safety in use, see Declaration of Incorporation. |
| For indoor use only |  |

5.1 Door weight in relation to performance level

## Plastic wheels

| Performance level | Main control | Sealing type | Door weight [kg] |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  | Single | Bi-parting |
| High performance | Escape | Normal seal | $2 \times 45$ | $4 \times 45$ |
|  |  | Tight seal | $2 \times 35$ | $4 \times 45$ |
|  | Non-escape | Normal seal | $2 \times 45$ | $4 \times 45$ |
|  |  | Tight seal | $2 \times 45$ | $4 \times 45$ |
| Exceptional performance |  | Normal seal | $2 \times 45$ | $4 \times 45$ |
|  | Non-escape | Tight seal | $2 \times 45$ | $4 \times 45$ |
|  |  | Normal seal | $2 \times 45$ | $4 \times 45$ |
|  |  | Tight seal | $2 \times 45$ | $4 \times 45$ |

## Steel wheels

| Performance level | Main control | Sealing type | Door weight [kg] |  |
| :--- | :--- | :--- | :--- | :--- |
|  |  |  | Single | Bi-parting |
| High performance | Escape | Normal seal | $2 \times 75$ | $4 \times 80$ |
|  |  | Tight seal | $2 \times 35$ | $4 \times 60$ |
|  | Non-escape | Normal seal | $2 \times 80$ | $4 \times 80$ |
|  |  | Tight seal | $2 \times 45$ | $4 \times 60$ |
| Exceptional performance |  | Normal seal | $2 \times 80$ | $4 \times 80$ |
|  |  | Tight seal | $2 \times 80$ | $4 \times 65$ |
|  | Non-escape | Normal seal | $2 \times 80$ | $4 \times 80$ |
|  |  | Tight seal | $2 \times 80$ | $4 \times 65$ |

### 5.2 Classification to DIN 18650-1

| Classification to DIN 18650-1 |  |  |  |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| Digit 1 | Digit 2 | Digit 3 | Digit 4 |  | Digit 5 | Digit 6 | Digit 7 | Digit 8 |
| 2 | 3 | 2 | 0 |  | 1,2,3 | 1,2 | 1,2,4 | 4 |
| Type of drive, digit 1. |  |  | 2 sliding door drive |  |  |  |  |  |
| Drive durability, digit 2. |  |  | 31 | 1000000 test cycles, at 4000 cycles/day |  |  |  |  |
| Type of door leaf, digit 3 . |  |  | 2 sl | sliding door |  |  |  |  |
| Suitability for use as a fire protection door, digit. 4 |  |  | 0 n | not suitable for use as a fire protection door |  |  |  |  |
| Drive safety devices, digit 5. |  |  | 1 fo | force limitation |  |  |  |  |
|  |  |  | 2 c | connection for external safety systems |  |  |  |  |
|  |  |  | 3 low | low energy |  |  |  |  |
| Special requirements for drives/functions/fittings, digit 6. |  |  | 1 in | in escape routes with a break-out system |  |  |  |  |
|  |  |  | 2 in |  | in escape routes without a break-out system |  |  |  |
| Safety at door leaf or leaves, digit 7 |  |  | 1 w | with sufficiently dimensioned safety distances |  |  |  |  |
|  |  |  | $2{ }^{2}$ | with protection to prevent fingers being crushed, shorn off or drawn in |  |  |  |  |
|  |  |  | 4 with presence sensor |  |  |  |  |  |
| Ambient temperature, digit 8 |  |  | 4 t | temperature range as specified by the manufacturer |  |  |  |  |

## 6 Design and function description

### 6.1 Design

The sliding door operator EM PSL150-T works electromechanically. The motor, control unit, transmission-and optional emergency unit and electromechanical locking device-are all assembled in a support beam with an integrated cover. The motor and gear box transmit movement to the door leaves by means of a tooth belt. The door leaf is fitted to a door adapter/carriage wheel fitting and hangs on a sliding track. Movement of the bottom of the door leaf is controlled by the floor guides.

### 6.2 Function

Opening
When an OPENING IMPULSE is received by the control unit the motor starts and transmits movement to the door leaves, which move to the open position.

Closing
The closing starts when no OPENING IMPULSE is received and the HOLD OPEN TIME has run out.
$6.3 \quad$ Safety functions integrated in the operator
To permit safe passage between closing doors, the doors immediately reverse if an obstruction is detected, then resume their interrupted movement at low speed to check whether the obstruction has disappeared or not. If an obstruction is detected while the door is opening, the doors immediately stop and then close after a time delay.

### 6.4 Microprocessor for precise control

The microprocessor has a routine for self-monitoring, which detects any interference or faulty signals in door operation. If an input signal does not correspond to the preprogramming, the microprocessor automatically takes necessary actions to ensure safe door operation.

Emergency escape
The EM PSL150-T can be combined with an emergency unit that automatically opens or closes the doors in the event of a power failure and can also be interfaced with the fire alarm or smoke detector. Safety can be further reinforced by incorporating a break-out fitting. This enables the doors and side screens to swing outwards in an emergency situation by applying a defined pressure at the front edge.

Doors used for emergency escape in buildings such as hospitals and homes for elderly people may not be locked or put in programme selection OFF.

## 7 Models

## Two main models are available:

- EM PSL150-T-2; for bi-parting doors, consisting of two pairs of door leaves which are sliding away from each other to form a common door opening.
- EM PSL150-T-1; for single sliding doors with a pair of sliding door leaves.

EM PSL150-T-2 (bi-parting)


EM PSL150-T-1 (single sliding, right opening)


EM PSL150-T-1 (single sliding, left opening)


## Third party door systems



FW = Frame width
$\mathrm{CL}=$ Cover length (incl. end plates, $2 \times 2 \mathrm{~mm}$ )
COW = Clear opening width
SW = Side screen width
TDW = Telescopic door leaf width

## 8 Part identification



| No. | Description | No. | Description |
| :---: | :--- | :---: | :--- |
| 1 | Mains connection | 13 | Tension wheel |
| 2 | Power supply unit (PSU 75/PSU 150) | 14 | Door stop |
| 3 | Drive unit (HDD/DD) | 15 | Cover |
| 4 | Main control unit (MCU/MCU-ER) | 16 | Operation mode selector (OMS) |
| 5 | l/O Unit (IOU) | 17 | Support beam |
| 6 | Battery (EEU 12/EEU 24) | 18 | Lock |
| 7 | Door carriage | 19 | Cover lock |
| 8 | Door adapter | 20 | Cable inlet |
| 9 | Transmission bracket (high) | 21 | Track |
| 10 | Transmission bracket (low) | 22 | Steel wire |
| 11 | Belt clamp | 23 | Fixed stay |
| 12 | Tooth belt |  |  |

## $9 \quad$ Space required

Frame doors by others EM Slim

$\mathrm{COH}=$ Clear opening height
$\mathrm{DH}=\quad$ Door height (incl. door adapter)
FFL $=\quad$ Finished floor level
Max. 302


## 10 Pre-installation

10.1 General tips/Safety concerns


In all instances, where work is being done, the area is to be secured from pedestrian traffic, and the power removed to prevent injury.

- If there are sharp edges after drilling the cable outlets, chamfer the edges to avoid damage to the cables.
- For enhanced security and vandalism protection, always mount the operator access in the interior of a building whenever possible.
- Make sure the ambient temperature is in the range specified in section Technical specification.
- Make sure that the power is off before installing.
- Make sure that the door leaf and the wall are properly reinforced at the installation points.
- Unpack the operator and make sure that all parts are delivered in accordance with the packing note and that the operator is in good mechanical condition.
- Ensure proper material is being used for the door leaves and that there are no sharp edges. Projecting parts shall not create any potential hazards. If glass is used bare glass edges shall not come in contact with other glass. Toughened or laminated glass are suitable glasses.
- For support beam length over 5 m , remove the wheel holders and motor, or two technicians are needed.
- Ensure that entrapment between the driven part and the surrounding fixed parts due to the opening movement of the driven part is avoided. The following distances are considered sufficient to avoid entrapments for the parts of the body identified;
- for fingers, a distance greater than 25 mm or less than 8 mm
- for feet, a distance greater than 50 mm
- for heads, a distance greater than 200 mm
- and for the whole body, a distance greater than 500 mm
- Danger points shall be safe guarded up to a height of 2.5 m from the floor level.
- The operator shall not be used with a doorset incorporating a wicket door.


It is not possible to replace an EM operator component with a component from a different brand.

## 11 Mechanical installation

### 11.1 Checking

Check that the fixing material and the upper part of the door leaf have the necessary reinforcements and that the floor is level and smooth.

The beam/wall used to fix the support beam must be flat and smooth. If necessary use Entrematic Nordic mounting spacers behind the support beam to keep its straightness.



1 Aluminium profile system
A Steel or aluminium reinforcement or rivet nut
2 Plasterboard wall
B Wood reinforcement
3 Reinforced concrete wall and brick wall

C Expansion-shell bolt (for brick wall min. M6x85, UPAT PSEA B10/25)

| Base material | Minimum requirements of wall profile* |
| :--- | :--- |
| Steel | $5 \mathrm{~mm}^{* *}$ |
| Aluminium | $6 \mathrm{~mm}^{* *}$ |
| Reinforced concrete | min .50 mm from the underside |
| Wood | 50 mm |
| Brick wall | Expansion shell bolt, min. M6x85, UPAT PSEA B10/25 <br> min. 50 mm from the underside |

[^0]
## Tools required

- Set of metric box spanners and wrenches ( $2 \times 10 \mathrm{~mm}$ wrench)
- Spirit level
- Tape measuring tool
- Power drill and set of drill bits, Hammer drill
- Cone cutter drill (step drill)
- Screw driver Torx (T10, T20, T25 and T30)
- Small flat blade screw driver for wire connection
- Phillips screw driver
- Centre punch
- Wire stripper
- Side cutter (for wire cutting)
- Torque wrench
- Cable strap tightener
- Steel wire (for pulling cables)
- Pencil (for marking)
- Cloth or brush (for cleaning)


### 11.2 Installation examples to consider during installation

Note! See the local building regulations for each country, with regards to the permissible minimum opening width, that shall be followed.

## Recommended installation (EM PS)

To reduce the risk for shearing of finger the jamb is used as door stop for closing and labyrinth sealings are used between door leaf(1) and fixed screen (2). The door leaf(1) can be opened fully and aligns with the fixed screen (2) if the side light is 100 mm wider than the door.

1 Door leaf
2 Fixed screen
3 Operator
COW = Clear opening width
LAP = Overlap (profile width)


## Alternative installation of door system (by others than EM PS)

The distance measured between the glass pane of the door leaf (1) and the profile of the fixed screen (2) shall not exceed 8 mm . If the distance is more than 8 mm the leading edge of the door leaf (1) must not pass the mullion of the fixed screen (2) but stop at least 25 mm before.


1 Door leaf
2 Fixed screen
3 Operator COW = Clear opening width LAP $=$ Overlap (profile width)

The safety distances measured between the secondary closing edge (4) and surrounding fixed parts (5) are shown in the illustrations below.

If the distance between the door and wall/side light is 100 mm or less, there shall be at least 200 mm between the door and a opposing surface when the door is in full open position. Safety distance for head or equip the operator with side presence sensors or pocket screens.
If the distance is more than 100 mm between the door and wall/side light, there shall be at least 500 mm between the door and a opposing surface when the door is in full open position. Safety distance for body or equip the operator with side presence sensors or pocket screens.


4 Closing edge
5 Fixed parts

If the distance is more than 100 mm but less than 150 mm between the door and the wall the speed of the door has to be reduced acording to PRA-0004 or equip the operator with side presence sensors or pocket screens.


## Sensor adjustment

This is an example of how the mounted sensors This is how the presence field of the sensor is shall be adjusted. tested to fulfil the standards according to EN 16005 and DIN 18650.

11.3 Installing/removing the cover, standard cover lock

Open cover


## Secure and unsecure cover

Secure and unsecure the open cover as shown below.


## Close cover

(1)

(2)

(3)



## New cover latch

In the illustrations above the old cover latch is used. The illustration below shows the new cover latch and how it is attached.

11.4 Installing/removing the cover, optional cover lock

## Open cover

(1)

(2)

(3)


## Close cover

(1)

(2)

(3)


### 11.5 Installing the door adapter on top of the door leaf(frame doors by others)

For Entrematic Nordic doors the door adapters and door holders are factory-mounted, proceed to page 29.
a If necessary cut the door adapter (1) to correspond with the door leaf width.
b Make sure that the upper part of the door leaf (2) is sufficiently reinforced.
c Place the dooradapter(1) on top and centre of the door leaf(2). Door leaf(2) with bigger depth than 50 mm place the door adapter (1) aligned with the outer side of the door.
d Mark on the door leaf (2) after the pre-drilled slotted holes. One slotted hole in each group of three has to be used as the door adapter carries the whole weight of the door leaf (2).
e Drill and thread for M6 or use self-tapping screws (Taptite) in the door leaf(2).
f The door adapter (1) can be roughly adjusted for depth, $\pm 5 \mathrm{~mm}$, in relation to the door leaf (2). This rough adjustment is to be carried out when the door adapter (1) is fitted on the door leaf.
g The distance "A" serves to ensure the correct depth installation. This information is delivered with the door system.
h Tighten the door adapter (1).
If a break-out unit is to be installed, a special break-out adaptor has to be ordered and then cut to size. See separate Installation and Service Manual for PSB.


1 Door adapter (standard)
2 Door leaf

### 11.6 Installation of support beam

## Marking and fixing

Determine the installation height from the highest point of the finished floor:
a Measure the door leaf height inclusive the door adapter.
b Add $\mathbf{1 0 8} \mathbf{~ m m}$ or $\mathbf{1 2 1} \mathbf{~ m m}$ if a 13 mm surface mounted threshold/floor guide track is installed.
c Mark the installation height on the wall as determined under items a) and b) as shown in the picture below.
d Drill the hole, tap or plug for the key hole screw.
e Hang up the support beam in the keyhole and tighten gently.
f Make sure that the support beam is level and compensate for possible sag in the ends. Mark the rest of the fixing holes. (Note that some holes can be covered by other components that first must be removed or slid to the side.)
g Tilt or remove the support beam.
h Drill the holes, tap or plug them.
i If the wall is uneven, compensate by hanging spacers around the bolts before they are tightened.
j Fix the support beam using bolts.
k Make sure to clean the support beam and sliding track thoroughly.


Figure 1: Installation height
Also see page 18.

### 11.7 Mount the secondary track onto the slow moving door

a Remove the wheel holders (1).
b Loosen all the screws (2) on the secondary track (3) so the bar (4) is loose.
c Slide the bar (4) into the door adapter on the slow moving door until the tube (5) docks towards the door.
d Make sure that the door holder and secondary track is completely in line with the door leaf.
e Tighten all the screws (2) with 8 Nm .


1 Wheel holder
2 Screw
3 Secondary track
4 Bar
5 Tube
6 Shim
For more information on the secondary track see Replacement of secondary track on page 105.
11.8 Installing the door holders on the door adapter (frame doors by others)
11.8.1 Slow moving door
a Remove the height adjustment fastening screw(1) and the height adjustment cam (2).Remove the wheel holder (4) from the door holder (3).


1 Height adjustment fastening screw
2 Height adjustment cam
3 Door holder
4 Wheel holder
b Maximum distance between the side light/wall and the centerline of the door adapter (5) on the slow moving door leaf is 40 mm .


5 Door adapter

11.8.2 Fast moving door
a The door holder for the fast moving door shall be rotated in the same way as for the slow moving door.
b Fasten the door holder (3a) at a distance A from the trailing edge of door leaf (6), see picture below.

Note! If a lock is to be mounted, the distance B is necessary. For more information about installing a lock, see Mounting the lock on page 110.
c Bi-parting door:
Fasten the door holder (3b), on the fast moving door, at a distance B from the estimated centre line $\&$ between the doors.

## Single door:

Fasten the door holder (3b), on the fast moving door, at a distance B from the estimated centre line $\mathcal{E}$ between the door leaf(6) and the slam post.

Note! Make sure that the door holders (3) are completely in line with the door adapter (5).


3 Door holder
5 Door adapter
6 Door leaf

| LD, LDP, LDB | A (mm) | B* $^{*}$ (mm) | Max distance** (mm) |
| :--- | :---: | :---: | :---: |
| Normal Wheelholder | 31 | 66 | 9 |
| Normal Wheelholder | 31 | 73 | 2 |
| Short Wheelholder | 11 | 46 | 9 |
| Short Wheelholder | 11 | 53 | 2 |
| *Bx2 between the door holders on a biparting door. <br> CL is the estimated center line between the doors or door and door post. <br> **Max distance $=$ the distance a door leaf can move when the door is in locked position. |  |  |  |

## Part identification door carrier



1 Height adjustment fastening screw
2 Height adjustment cam
3 Door holder
4 Depth adjustment
5 Door holder fastening screw
6a 2-Wheel holder
6b 2-Wheel holder, short
6c 4-Wheel holder
$7 \quad$ Carriage wheel
8 Anti-riser device

- left illustration, Engaged
- right illustration, Disengaged

Secondary bogie
Clips, single wheel
Clips, bogie wheels

Note! If the door width is less than 540 mm , the operator will be equipped with a short wheel holder.

| Wheels | Door weight, bogie | Door weight, double bogie |
| :--- | :--- | :--- |
| Plastic | $0-45 \mathrm{~kg} / \mathrm{leaf}$ | - |
| Steel | $45-60 \mathrm{~kg} / \mathrm{leaf}$ | $60-80 \mathrm{~kg} / \mathrm{leaf}$ |

Note! If door height / door width ratio (DH/DW) for the fast moving door is more than 3.5, double bogie wheels will be delivered. If the door is equipped with short wheel holder, single bogie steel wheels will be delivered.
DH/DW ratio does not apply to the slow moving door.
11.9 Hanging and mounting the slow moving door leaves
a Loosen and remove the height adjustment fastening screw (1) and the height adjustment cam (2) from the wheel holders (3).

Note! The anti-riser devices shall be engaged on the wheel holder (3). See page 34.
b Raise the door leaf (4) and place it carefully over the floor guide, if installed.
c Slide the wheel holders (3) sideways, in the beam, until they are aligning with the door holders.
d Reinstall the height adjustment fastening screw (1) and the height adjustment cam (2) into the door holders and tighten gently.


1 Height adjustment fastening screw
2 Height adjustment cam
3 Wheel holders
4 Door leaf

### 11.10 Height adjust the slow moving doors

The door can be height adjusted $+/-8 \mathrm{~mm}$ by turning the height adjustment cam (2).
a Indication on the cam show what height the door is adjusted to (in mm).
Note! The illustration below shows a zero adjusted cam.
b Adjust all cams to the same value on the slow moving doors.
c Check that the door(s) is hanging horizontally. It is very important that the door leaves are parallel with the fixed panel.
d To increase the height of the door turn the cam in the direction shown by the arrow UP on the cam.
e When the door leaf is $6-8 \mathrm{~mm}$ above the highest point of the Finished Floor Level (FFL), the door is properly adjusted. Tighten the height adjustment fastening screw (1) with 18 Nm .


### 11.11 Installation of telescopic wire

## Cutting the wire length

a Measure the distance $\mathbf{D}$ between the outmost point of the two wire pulley wheels (1).
b Calculate the total length $\mathbf{L}$ of the wire (2) with the formula below.
c Cut the wire (2) at the total length $\mathbf{L}$.

$L=$ Total length of wire
$\mathrm{L}=\mathrm{D} \times 2+200 \mathrm{~mm}$
1 Pulley wheel
2 Wire

## Threading the wire

(1)
a

(2)

(3)

(4)


2 Wire
3 Grommet
4 Reel
b Check that the wire (2) is not twisted and tangled.


2 Wire
c Tighten the nut (5) and then the wire lock screw (6), located inside the torx screw.

d Loosen the nut (5), after tensioning the wire lock screw (6).
e Cut of the excess length of the cable.
f With the doors in closed position, mount the wire holder bracket in the C-track, centered over the slow moving door leaf and tighten the screws (7) with a torque of 10 Nm .

Note! If any part of the control system is in the way of the wire holder bracket, move it and connect with supplied extension cables.

g Pull the wire (2) around the pulley wheels (1) and click the wire inside the fender wings (8).

h
i Tighten the wire (2) with a torque of 2 Nm by turning the wire reel (4) clockwise with a Torx screwdriver.
j Tighten the nut (5).
11.12 Install the fast moving doors
a Height adjust all cams on the fast moving doors. All cams, on the fast moving doors, shall be adjusted to the same value and be align with the slow moving doors.

Note! The cams on the slow moving doors and the cams on the fast moving doors will always differ.

Note! When the cam on the fast moving door is adjusted to +5 mm , the door is level with the slow moving door.
b Put the doors in closed position.
c Check that the door leaf is parallel (no gap at the top or bottom).


## FFL $=$ Finished floor level



### 11.13 Installation of Entrematic Nordic floor guides (frame doors by others)

The floor guides can be adjusted depthwise about $\pm 4 \mathrm{~mm}$ after being installed, using the eccentric nut underneath the plastic block.

Note! Before installing the floor guide make sure that the plastic block is adjusted to the middle position to ensure full adjustability ( $\pm 4 \mathrm{~mm}$ ).

## Installation

a Bi-parting doors
Push the fast moving outer doors together and slide them until their meeting point is aligned with the centre of the clear opening width.

## Single sliding doors

Slide the fast moving outer door leaf to closed position.

## Fast moving outer door leaf

The door guides are fitted on the underside of the door leaf. The door leaf can be adjusted $\pm$ 1.5 mm horizontally by turning the eccentric pin (4) $180^{\circ}$. For vertical adjustment, turn the pin complete turns.
Tighten the lock screw (5) after the adjustment of the door leaf, to secure the setting.

## Slow moving inner door leaf

The floor guides can be adjusted depthwise about $\pm 4 \mathrm{~mm}$ after being installed, using the eccentric nut underneath the plastic block (1).
Before installing the floor guide make sure that the plastic block (1) is adjusted to the middle position to ensure full adjustability ( $\pm 4 \mathrm{~mm}$ ).
b Fit the floor guide so that the plastic block is in line with the trailing edge of the door leaf when in the closed position as shown in the illustration below, and depthwise (the B measurement) in accordance with the instructions from the door manufacture.


C Mark the position for the floor guide.
d Push the door leaf sideways to clear the space.
e Mark, drill and plug the three holes and fasten the floor guide.


1 Plastic block
2 Door guide track
3 Slow moving door leaf

4 Eccentric pin
5 Lock screw
6 Fast moving door leaf
f Check that the door runs freely over the floor guide without friction.
g If a weather brush is used on the lower edge of the door leaf, it should only lightly touch the floor.

### 11.14 Depth adjustment of the door leaves

a The distance $\mathbf{A}$, between the top of the door leaf and the fixed screen, and the distance $\mathbf{B}$, between the door leaves, are to be adjusted by loosening the two screws connecting the door holder (1) to the door adapter (2).
b The holes in the door holder (1) are slotted and the door leaf/adapter (2) can be adjusted $\pm 7$ mm.
c The distances $\mathbf{A}$ and $\mathbf{B}$ shall be 22 mm for third party doors and 20 mm for EM Slim System.
d For frame doors made by others the distances $\mathbf{A}$ and $\mathbf{B}$ are supplied by the manufacture. The distances depends on the door leaf thickness and draught excluders. When a draught excluder is used between the door leaf and the fixed screen, it should seal equally for the total vertical height.

Note! Make sure that the door holder (1) is completely in line with the door adapter (2).
Note! The door holders (1) can be turned depending on door type. See illustration below.
e The distance $\mathbf{C}$ shall be equal to $\mathbf{A}$ and distance $\mathbf{D}$ equal to $\mathbf{B}$. With EM floor guide series, FGB or GS on frame doors made by others, the distance $\mathbf{C}$ can be adjusted $\pm 4 \mathrm{~mm}$ with the eccentric nut on the floor guide and the distance $\mathbf{D}$ can be adjusted $\pm 1.5 \mathrm{~mm}$ with the eccentric pin.

Frame doors by others
EM Slim System


C-C


D-D

1 Door holder
2 Door adapter (integrated in the door leaf for EM Slim System)

### 11.15 Connect the fast moving door to the slow moving door

a Remove the upper part of the transmission bracket (1) from the wheel holder (2).


1 Upper part of the transmission bracket
2 Wheel holder
b Position both door leaves in closed position.
c Put a mark on the wire (3) in line with the height adjustment fastening screw (4) of the fast moving door.

Note! The wheel holder, where the above mentioned height adjustment fastening screw (4) is located, is on the leading edge on an double door and a single left opening door, or on the trailing edge on a single right opening door.


3 Wire
4 Height adjustment fastening screw
d Move the fast moving door leaf out of the way without changing the slow moving door position. Attach the wire catcher (5) on the lower wire (3), centered over the mark on the upper wire (3). The mark can be seen through the slot in the bracket, see the illustration below.


1 Upper part of the transmission bracket
3 Wire
5 Wire catcher
e Fasten the lower part of the transmission bracket (7) on the wheel holder (2).


2 Wheel holder
7 Lower part of the transmission bracket

## f For bi-parting and single left opening doors:

- Fasten the upper part of the transmission bracket (1) on the lower part of the transmission bracket (7) placed on the wheel holder (2) in the leading edge.

Note! For bi-parting doors turn the right belt holder bracket (6) $180^{\circ}$. The right belt holder bracket shall catch the upper belt.


1 Upper part of the transmission bracket
2 Wheel holder

6 Beltholder bracket, universal
7 Lower part of the transmission bracket

## For single right opening doors:

- Fasten the upper part of the transmission bracket (1) on the lower part of the transmission bracket (7) placed on the wheel holder (2) in the trailing edge.


1 Upper part of the transmission bracket
2 Wheel holder
6 Beltholder bracket, universal
7 Lower part of the transmission bracket
g For double slider, repeat the steps (a to e) with the other door leaf.
h Move the door to closed position.
i Loosen the height adjustment screws (8) and the depth adjustment screws (9).


8 Height adjustment screw
9 Depth adjustment screw
j Adjust the transmission brackets height and depth towards the wire.
k Tighten the height adjustment screws (8) and the depth adjustment screws (9), on the transmission bracket.

I Put the door in open position. Check that the wire catcher is not pulling the wire when moving the door.
$m$ Check that the door can be opened to the right position. Adjust if necessary by loosen the fixed stay so it can slide in the C-track and adjust the doors in open position according to EN 16005, see page 22.
11.16 Installation of components and electrical wiring
a Start from the left side of the operator, loosen and slide the mains connection and the power supply sideways to obtain 65 mm from the left side of the support beam to the left side of the power supply. Tighten the two fixing screws (1).


1 Fixing screw
b Tighten the nuts (2) on the drive unit by hand. No space between the nut (2), plastic washers (3) and the damper (4).


2 Nut
3 Plastic washer
4 Damper
c Install the drive unit with its outgoing shaft 350 mm from the left side of the support beam. Tighten the screws (5) with a force of $10 \mathbf{N m}$.
Start with the right screw and ensure that the drive unit is fixed in the beam. Continue with the left screw and visually ensure that this screw also is securely tightened in the beam.


5 Fixing screw
d Continue with the main control unit MCU or MCU-ER and keep a distance of 5-10 mm to the drive unit.

e If an I/O unit (IOU) shall be used make sure that the connector is fully connected to the MCU/MCU-ER.
f Fix the batteries, if fitted.
Note! Extension cables are available as accessories if MCU/MCU-ER, IOU or batteries must be installed with greater distances.
11.17 Installation of tension wheel assembly
a Tighten the nuts (1) on the belt tension by hand. No space between the nut (1), plastic washer (2), screw (3) and the tension frame (4).


6 Adjustment screw
c Put the belt tension with the nuts (1) in the C-track (5). Tighten the screws (3) gently. It shall be possible to slide the tension wheel assembly side ways in the C-track (5).


### 11.18 Placement of the transmission bracket

## For bi-parting and single left opening doors

The upper transmission bracket shall be attached to the carriage wheel holder on the leading edge of the right door.
The lower transmission bracket shall be attached to the carriage wheel holder on the leading edge of the left door.


1 Upper transmission bracket
2 Lower transmission bracket

## For single right opening doors

The upper transmission bracket shall be attached to the carriage wheel holder on the trailing edge of the door.


1 Upper transmission bracket

Note! Tighten with a maximum force of 7 Nm .

### 11.19 Attachment of tooth belt fitting

a The tooth belt (1) is delivered separately and is pre-cut to the right length. Route the belt (1) around the drive unit pulley (2) and around the tension wheel (3).
b For bi-parting and single right opening doors the belt ends are joined with the belt clamp (4) in the upper part of the belt. Single left opening door is joined in the lower.
c Click the belt clamp (4) into position in the upper transmission bracket (5).


1 Tooth belt
2 Drive unit pulley
3 Tension wheel

4 Belt clamp
5 Uppertransmission bracket
11.20 Checking and adjusting the belt tension

If the belt tension has to be corrected, proceed as follows:
a Remove the slack reducer, if fitted.
b Loosen the fixing screw (1) in the middle of the tension wheel (5) without removing it.
c Screw the adjustment screw (2) to its outmost position.
d Loosen the tension wheel assembly fixing screws (4).
e Tension the belt by pulling the tension wheel assembly by hand.
f Tighten the tension wheel assembly fixing screws (4) with a torque of $\mathbf{1 0} \mathbf{~ N m}$.
g Tighten the belt tension adjustment screw (2) until there is a gap of approx. 1-2 mm between the lock nut (3) and the bracket according to illustration below, but not further. Be sure not to overtighten, otherwise the adjustment screw (2) might damage the tension wheel (5).
$h$ Retighten the fixing screw (1) in the middle of the tension wheel (5) with a torque of $\mathbf{3 0} \mathbf{N m}$.
Note! Do not make any adjustment on the lock nut (3).


1 Fixing screw
2 Adjustment screw
3 Lock nut
4 Tension wheel assembly fixing screw
5 Tension wheel

### 11.21 Bi-parting operators

a Put doors in fully closed position. Make sure that the doors trailing edge is align with the side light.
b Put the belt clamp (4) centered over the lower transmission bracket (5).
c When centered snap the belt clamp (4) in place.
d Check door panels for proper centering in the fully closed and opened positions.


1 Tooth belt
2 Drive unit pulley
3 Tension wheel
4 Belt clamp
5 Lower transmission bracket

Note! There shall be a distance of 5-7 mm between the tubes on the slow moving doors.

### 11.22 Mount the doorstop

a Push the doors by hand to the desired opening.
b For EM Automatic Door Systems the door leaf can be fully open. For single doors, shearing of finger is reduced by using a jamb as a door stop in closed position. Labyrinth sealing is used between the trailing edge on the door leaf and the fixed side screen to prevent a finger trap.
See Alternative installation of door system (by others than EM PS) on page 22 for required measurements.
c Loosen the door stops (1), move them in against the wheel holders, and hold the door stop in position against the beam (2) then tighten screws (3) firmly.
d Tighten the screw (4) on one of the door stops (1) to secure the plastic track (5). If there is a screw (4) on the other door stop remove it.
e Check that the required opening and finger protection is achieved, see page 22.


1 Door stop
2 Beam
3 Door stop fastening screw
4 Screw (to secure the plastic track)
5 Plastic track

## f If the doors shall be aligned in open position:

- Mount the L-Bracket (6) on existing door stop (1) in the beam.


1 Door stop
3 Door stop fastening screw
6 L-bracket

## If the doors are not required to be aligned:

- Mount the extra door stop (1) on the secondary track to achieve required finger protection, see page 22.

11.23 Route the cables and attach the plastic cable holders, see illustrations below


1 Cable holder


2 Cable holder

### 11.24 Attachment of slack reducer

Attach the slack reducer between the eighth and ninth belt tooth on each side of the low transmission bracket. If two slack reducers are needed put the second slack reducer in the same way under the upper transmissions bracket.

Note! If needed, the operators will be delivered with slack reducer springs.

## Single doors

If the belt length is more than 4700 mm , there shall be one slack reducer.

## Double doors

If the belt length is more than 5700 mm , there shall be two slack reducers.

## In all other cases

In all other cases, then above, there will not be any slack reducers in the operator.

11.25 Attachment of product label

When properly installed and adjusted, attach the local product label on the right side of the lower part of the operator cover.


## 12 Electrical connections

Note! During any work with the electrical connections the mains power and the electrical emergency unit must be disconnected.

- Place the electric switch easily accessible from the operator. If a plug contact is used in the installation the wall socket shall be placed easily accessible from the operator.
- If the supply cord is damaged, it must be replaced by the manufacturer, its service agent or similarly qualified persons in order to avoid a hazard.


### 12.1 Mains connection

The incoming mains, which is a single phase $50 / 60 \mathrm{~Hz} \mathrm{AC}$ voltage between $100 \mathrm{~V}-10 \%$ and 240 V $+10 \%$ fuse 10 AT , is connected in the mains connection unit.
a Remove the protective lid (2).
b Connect the incoming mains power (4) through the strain relief (3) to the connection block (1) as shown in the illustration below.
c Put the protective lid (2) back in place.


Installer must properly ground door package! Improper grounding can lead to risk of personal injury.

> Mains power
> $100-240$ V AC
> $50 / 60 \mathrm{~Hz}, 10 \mathrm{~A}$


1 Mains connection block
2 Protective lid
3 Strain relief
4 Mains power


The mains connection (5) must remain unconnected until the wiring is completed. Then connect to the supply unit (6).

## 5 Connection cable <br> 6 Power supply unit

12.2 Electrical units
12.2.1 Power supply unit (PSU 75/PSU 150)

Two different main power supplies are available, 75 W and 150 W .

$$
\text { PSU } 75
$$


(Marked with yellow label)

PSU 150

(Marked with green label)
12.2.2 Drive unit (HDD/DD)

The drive unit is available in different versions:


Dual drive (DD)
2 X GR 63X55

12.2.3 Main control unit (MCU/MCU-ER)

The main control unit has the connection for the power supply, drive unit, operation mode selector, activation units, electromechanical lock and batteries. An installer interface with a two digit display and four push buttons is used for function selection, adjustments and for troubleshooting. See page 71 for details.

The main control is available in two different versions.

- MCU-ER - used in escape routes where EN16005 and DIN18650 applies
- MCU - used in all other applications

> MCU-ER


MCU


The MCU/MCU-ER has two labels, a Hardware label (1) and a Software label (2).
The hardware label states revision of the MCU/MCU-ER and applies to PCB or hardware changes.
The software label states the software version. In the MCU there are two different software versions. and in the MCU-ER there are three different software versions.

Note! Newer MCU/MCU-ER's will not have all software versions stated. Instead the software release version is stated.


1 Hardware label
2 Software label
12.2.4 Additional electronic units can be connected for extra functionality

Battery unit 12 V (EEU 12)


For opening or for fire closing a 12 V battery can be connected that automatically opens or closes the door in the event of a power failure. For higher speed, the 24 V battery below is recommended and is also a demand to conform with authority demands for escape routes.

## Battery unit 24 V (EEU 24)



For emergency opening or for fire closing a 24 V battery can be connected that automatically opens or closes the door in the event of a power failure. This battery can also be used for continued normal operation during short power failures (convenience mode). The fuse in the cable harness is 10 AT.

## I/O unit (IOU)

The IOU has two labels, a Hardware label (3) and a Software label (4).
The hardware label states revision of the IOU and applies to PCB or hardware changes.
The software label states the software version.
Note! Newer IOU's will not have the software version stated. Instead the software release version is stated.


3 Hardware label
4 Software label

For extra functionality like

- close or robbery impulse
- nurse impulse
- open/close impulse
- emergency open impulse (fireman's opening)
- bi-stable lock
- espangolette lock
- connection of optional operation mode selector
- fire impulse
- sustainable function off
- relay output for external error or status indication, maximum 15W, 42VAC / 30 VDC (SELV), resistive load only
- interlock off (interconnected operators)
- interlocking
- second monitored inner impulse
- repeated fire closing
- pharmacy impulse 1 and 2
- mode selector disable impulse



## MCU/MCU-ER




Function Select TB:2 Close or robbery impulse/LDE down/Inner impulse 2
0 V

* 1 wire monitoring = Presence, stop, inner (and/or) outer impulse monitoring
** Key impulse can generate a battery wake up if mains power is off and battery is fitted. The door can open or open/close


### 12.3 Connection of activation and safety units

See sensor manuals for mounting and adjustments. Protective device shall comply with EN 12978.


```
A = Brown
B = Green
C = White
D = Orange
E = Red
F = Blue
G = Yellow
H = Pink
I = Grey
J = Black
K = Grey/Pink
L = Red/Blue
```

Common dip switch setting for inner sensors, dip switches shown are set to ON :
EMSC32-M: 1, 3, 5, 12, (11=NO)
EMSC31-M: 1, 3, 5, 8, 9, (7=NO), (15=Lookback)

Common dip switch setting for outer sensors, dip switches shown are set to ON :
EMSC32-M: 1, 3, 12, (11=NO)
EMSC31-M: 1, 3, 8, 9, (7=NO), (15=Lookback)
EMSC31-E: 1, 3, 8, 9, (7=NO), (15=Lookback)
12.4 Connection of presence activation units


Common dip switch setting for side presence sensors, dip switches shown are set to ON:
EMSP32-M: 1, 3, 10

### 12.5 Connection of accessories



## 13 Start-Up

Start-up and adjustment must be carried out in the following order when the operator is installed.
a Only connect PSU, motor, lock, battery and operation mode selector.
b Connect the mains plug to the control unit.
c Push and hold the learn button for 2 seconds. Release the learn button when there is a flashing "L" in the display.
d The learn cycle starts 2 seconds after the learn button is released.
e When the learn is finished the display can show different parameters that could not be set automatically during the learn cycle. These parameters shall be entered by the installer. See page 73.
f Give a Push And Go and see that the door runs as expected.
g Disconnect the power and connect all accessories such as well adjusted sensors and breakout switches.
$h$ Connect the mains plug to the control unit.
i Check that the sensors are in standby mode, deactivated, and there is no traffic in the door opening.
j Push the Learn button and make a learn. In the second learn all the accessories and sensors shall be learned into the control unit.
k Check the door movement by giving an impulse on the operator.
I If necessary adjust the door speed parameters to the required speeds.
$m$ Check that the installation complies with valid regulations and requirements from the authorities, see page 22.
n For parameters that shall be adjusted to comply with EN 16005 and DIN 18650 see page 119, Escape route according to EN16005 or DIN 18650.

### 13.1 Adjustments and selection of special operating functions

The main control unit has a two-digit display that shows text and/or digits. On the right side of the display are four push buttons. The display can show 4 different modes:
a Parameter mode. In Parameter mode the display shows parameters from 00 to C6. A parameter control different behavior in the operator.
b Value mode. In Value mode the display shows values from 00-99. A value sets how a parameter shall act.
c Error mode. Error mode shows what error group and error code that is active.
d Status mode. Status mode shows what impulses that are active in to the MCU.


1 Up (to step up in parameter or value menu)
2 Select (enters into parameter or value menu and program a value into memory)
3 Down (to step down in parameter or value menu)
4 Learn/Exit (Learn has 3 functions, 1 quick learn, 2 Normal learn, 3 default setting, Exit jumps out from value menu without saving or parameter menu)
Up and Down buttons steps between the different parameters or values.
Select steps from the standby mode into the parameter mode or steps from the parameter mode into the value change mode. In the value change mode, pushing Select, will program the selected value into the selected parameter and step back to the parameter mode.
Learn/Exit button initiate a learn of the control unit if the MCU is in the standby mode. Learn/Exit button will exit the value programming mode and enter the parameter mode without saving the value. Learn/Exit button will exit the parameter mode and enter the standby mode.


Fingers may be trapped by the belt transmission bracket. Set the operation mode selector(OMS) to OPEN before doing any configurations with the buttons.

## Active error

E1 = flashing letter E followed by a digit displays an active error (1-9). The digit shows the main type of error. The display switches between this main error and a two digit number to specify the error.

If several errors are active they are displayed in a sequence. Errors are cleared by a RESET from the operation mode selector (OMS) or by turning off and on the mains power. For a detailed description of errors, see Troubleshooting on page 121.
13.2 The Learn function can be one of three different types

1 Push and hold the Learn/Exit button for more than one and less than two seconds, then each connected electronic module is recognized.
2 Push and hold the Learn/Exit button for more than two seconds and the display flashes L. A complete Learn cycle will start after 2 seconds when the Learn/Exit button is released. The complete learn cycle includes the learn in point no. 1 .
The door will first close, start to open a short distance and close again. It will sense if an electromechanical lock is installed and also find out of which type it is. It will then open the door and during the opening it will calculate the friction in the system. It will stop in the fully open position and register the clear opening width. It will also register connected sensors and can judge whether they are monitored or not. After a $4-10$ seconds delay it will close again. During the closing it will automatically calculate the door weight and adjust the closing speed accordingly.
The following accessories/parameters are automatically detected and set during the learn cycle.

| Accessory/Parameter | Parameter number |
| :--- | :--- |
| Adjustment of closing speed according to ANSI/BHMAA156.10 standard. | 02 |
| Electromechanical lock and which type | $05,06,98$ |
| Controlling of connected sensors output, NO/NC | $07,08,27,28,46$ |
| If the sensors are monitored or not | $09,16,29,66,91$ |
| Battery and battery size | 41 |
| Measuring of clear opening width | 59 |
| Power supply type | 64 |
| Door type | 67 |
| Calculation of door weight | 68 |
| Calculation of friction in the system. | 69 |
| Second inner impulse | 93 |

When the learn cycle has ended the door will stay closed. If there are some parameters that couldn't be configured automatically during the learn cycle the door will open. The display will show first a "P" and then what parameter that couldn't be auto configured, e.g. whether the door is bi-parting or single sliding (parameter 67 Door Type). These parameters has to be configured by the installer.
1 Push the right button, Select, to start editing parameters.
2 Push the Select button once again and the value of this parameter is shown while flashing.
3 Push the Up or Down buttons to select the right value.
4 Push the Select button to confirm and program the selected value.
5 Continue to configure the rest of the unlearned parameters.
6 Push and hold the Learn/Exit button for more than two seconds and the display shows 'on'. After two seconds delay the door closes and is ready for operation or for further adjustments.
3 Push and hold the Learn/Exit button for more than ten seconds and the operator returns to default factory set parameters.
After 2 seconds the display starts to flash a L. After another 8 seconds the display shows de (de for default) and the control unit is factory set. 2 seconds after the button is released the display goes back to show what it showed before the start of the default setting.

### 13.3 Display test and configuring of parameters

a When the display shows "on", push the Select button and each of the two display windows make a rotating test pattern.
b Verify that all seven segments of the two display windows are lit during the test. If not there is a risk of misjudgment of the digits shown in a defective display.
c When the display test is finalized the display shows two steady digits indicating the first parameter.
d Push the Up or Down buttons to select the parameter to adjust.
e Push the Select button again to show the value of the selected parameter. The value is shown as two flashing digits.
f Push the Up or Down buttons to adjust the value in the allowed range.
g When the correct value is selected push the Select button again and the value will be programmed into the MCU memory.
h Push the Exit button once and leave the value editing without making any changes.
i Push the Exit button once again to leave parameter menu. The display shows 'on'. It is also possible to return to normal operation 'on' by waiting three minutes without pushing any button.

Note! The value is programmed into the MCU when pushing Select regardless if the value is changed or not. When a value is programmed into the MCU that parameter is excluded from the learn cycle. If a new learn is made the programmed parameter will remain unchanged.

To have the parameters included in the learn cycle again you have to make a default setting of the MCU, (see above).
Below is the available characters in the display. Observe 5 and $S$ are the same.

| Display | Character | Display | Character | Display | Character | Display | Character | Display | Character |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
|  | 0 |  | 5 |  | A |  | e |  | S |
|  | 1 |  | 6 |  | b |  | F |  | t |
|  | 2 |  | 7 |  | C |  | n |  |  |
|  | 3 |  | 8 |  | d |  | 0 |  |  |
|  | 4 |  | 9 |  | E |  | P |  |  |

13.4 Status indication on the display

Select status indication by setting parameter $5 \mathrm{E}=01$.
The display shows the different impulses that are active. The status viewing starts with showing St as for Status, then one or many numbers representing the different active impulses in to the operator.

The different impulses are:
$00=$ Key Impulse
$01=$ Innerimpulse
$02=$ Outer impulse
$03=$ Synchronisation impulse
$04=$ Interlockin impulse
$05=$ Presence impulse 1
$06=$ Presence impulse 2
$07=$ Side Presence impulse 1
$08=$ Side Presence impulse 2
$09=$ Stop impulse
$10=$ Emergency open impulse
$13=$ Close command
$14=$ Nurse impulse
$24=$ Push and Go impulse
$25=$ Open-Close impulse
$28=$ Fire impulse
$47=$ Interlock Disable

### 13.5 Configuration parameters (sorted after functionality)

Note! Some of the parameters below are not accessible, depending of different options installed.
For further explanations of parameters below, see page 81.

| FUNCTION parameters |  |  |
| :---: | :---: | :---: |
| Param. ID | Description | Range |
| MCU 5E | Status indication. Off(00)/ On(01) | 00-01 |
| MCU 5F | Default programming. Off(00)/ On(01) | 00-01 |
| IOU 9C | Pharmacy function. Off(00)/ On(01) | 00-01 |
| MCU 12 | Opening direction. CW(00)/CCW(01) | 00-01 |
| MCU 13 | Hold Force | 00-60 N |
| MCU 2A | Side Presence Function. Safe Speed(00) / Stop Door(01) | 00-01 |
| MCU 32 | Active Brake on Stop. Off(00)/ On(01) | 00-01 |
| MCU 33 | Push \& Go in EXIT Mode Selection. Off(00)/ On(01) | 00-01 |
| MCU 34 | Hold Force in EXIT and OFF Mode Selection. Off(00)/ On(01) | 00-01 |
| MCU 35 | Toggle Operation Mode Selector after Stop. Off(00)/ On(01) | 00-01 |
| MCU 47 | C-Switch Configuration. $\mathrm{NO}(00) / \mathrm{NC}(01)$ | 00-01 |
| MCU 53 | Operator Type. Slider(00) | 00 |
| MCU 54 | Service Needed Operating Hours | 00-60 h x 1000 |
| MCU 55 | Service Needed Opening Cycles | 00-50 cycles x100.000 |
| MCU 56 | Service Needed Locking Cycles | 00-50 cycles x10.000 |
| MCU 60 | Learn. Off(00)/On(01) | 00-01 |
| MCU 61 | Auto Width. Off(00)/ On(01) | 00-01 |
| MCU 62 | Partial Function. Opened(00)/ Closed(01) | 00-01 |
| MCU 6A | Interlock Function. Off(00)/ On(01) | 00-01 |
| MCU 6b | Synchronizing Function. Off(00)/ On(01) | 00-01 |
| MCU 6C | External Bus Device ID | 01-99 |
| MCU 6d | Extended Hold Open Time Function. Off(00)/ On(01) | 00-01 |
| MCU 6E | MMI Access code. 1 push(00), 4 push(01) | 00-01 |
| MCU 65 | Sustainable Drive Mode. Off(00) / On(01) | 00-01 |
| MCU 67 | Door Type. Single sliding(00)/ Biparting(01) | 00-01 |
| IOU 90 | Function Select TB:3. No function(00)/Nurse function(01)/LDE up(02) / Interlock out(03) | 00-03 |
| IOU 91 | Function Select TB:4. No function(00) / Open/Close function(01) / Interlock disable (02)/ Inner impulse 2 monitoring(03)/ Interlock in(04) | 00-04 |
| IOU 93 | Function Select TB:2. No function(00)/ Close function(01)/ LDE down(02) / Inner impulse 2(03) | 00-03 |
| IOU 99 | Function Select TB:6. No function(00)/Sustainable Disable(01)/Mode Selector Disable (02) | 00-02 |

## DRIVE parameters

| Param. <br> ID | Description | Range |
| :--- | :--- | :--- |
| MCU-ER <br> A0 | Escape Route Motor Configuration. 1-motor(01)/2-motor(02) | $01-02$ |


| DRIVE parameters |  | Range |
| :--- | :--- | :--- |
| Param. <br> ID | Description | $01-05$ |
| MCU 15 | Run Program. Smooth(01) to Max Performance(05) | $02-23 \mathrm{~N} \times 10$ |
| MCU 49 | Opening Max Force | $02-23 \mathrm{~N} \mathrm{x10}$ |
| MCU 4A | Close Kick Force | $02-23 \mathrm{~N} \mathrm{x10}$ |
| MCU 50 | Closing Max Force | $01-02$ |
| MCU 64 | Power Supply Type. 150 W(01)/75 W(02) | $01-40 \mathrm{~kg} \times 10$ |
| MCU 68 | Door Weight | $00-99 \mathrm{~N}$ |
| MCU 69 | Friction | 01 |
| MCU 70 | Motor Type. Heavy Duty(01) | $03-15 \mathrm{~W} \times 10$ |
| MCU 71 | Max Motor Power |  |


| EMERGENCY parameters |  | Range |
| :--- | :--- | :--- |
| Param. <br> ID | Description | $00-02$ |
| MCU 10 | Emergency Unit Monitoring. Off(00)/ Convenience Monitoring(01) / <br> Redundant Monitoring(02) | $00-01$ |
| MCU 36 | Emergency Action. Closing(00)/Opening(01) | $00-01$ |
| MCU 37 | Emergency Action in OFF Mode. Off(00)/ On(01) | $00-01$ |
| MCU 38 | Convenience Battery. Off(00)/ On(01) | $00-01$ |
| MCU 39 | Battery Wake-up. Open(00)/ Open/Close(01) | $00-02$ |
| MCU 3A | Lock Door After Fire Closing. Follow Mode Selector(00)/Always Un- <br> lock(01) / Always Lock(02) | $04-23$ hours |
| MCU 40 | Emergency Unit Test Interval | $00-02$ |
| MCU 41 | Battery Type. No battery(00)/12V(01)/24V(02) | $00-01$ |
| IOU 94 | Fire Impulse Function (I/O unit). Off(00)/On(01) | $00-01$ |
| IOU 95 | Emergency Open Impulse Function (I/O unit). Off(00)/On(01) | $00-01$ |
| IOU 96 | Emergency Button Configuration (I/O unit). NO(00)/NC(01) |  |


| OPERATION MODE SELECTOR parameters |  |  |
| :---: | :---: | :---: |
| Param. <br> ID | Description | Range |
| OMS B0 | Operation Mode Selector Variant, OMS-1. <br> 3 buttons with EXIT(01)/3 buttons with AUTO(02)/4 buttons(03)/ <br> 5 buttons(04) | 01-04 |
| OMS B1 | Operation Mode Selector Key Lock, OMS-1. Off(00)/ Hold for two sec(01) / Passcode(02) / | 00-02 |
| OMS B2 | Operation Mode Selector Service Indication, OMS-1. Off(00)/ On(01) | 00-01 |
| OMS B3 | Choose Priority of the operation mode selector, OMS-1. The lower the number the higher the priority. | 25-99 |
| OMS B4 | Choose group of the operation mode selector, OMS-1. | 00-10 |
| OMS B5 | Choose display mode of the operation mode selector, OMS-1. Show system mode(00) / Show local mode(01) | 00-01 |
| OMS B6 | Choose Terminal mode of the operation mode selector, OMS-1. The buttons on OMS is disabled(00)/The OMS adapts to system mode(01)/The OMS is setting the operation mode(02) | 00-02 |
| OMS B7 | Mode Selector, Self Service Indication, OMS-1. Off(00)/ On(01) | 00-01 |
| OMS B8 | Mode Selector, Key Impulse, OMS-1.Disabled(00)/Login Required(01) \| Enabled(02) | 00-02 |
| OMS C0 | Operation Mode Selector Variant, OMS-2. <br> 3 buttons with EXIT(01)/3 buttons with AUTO(02)/4 buttons(03)/ <br> 5 buttons(04) | 01-04 |
| OMS C1 | Operation Mode Selector Key Lock, OMS-1. Off(00) / Hold for two sec(01)/Passcode(02)/ | 00-02 |
| OMS C2 | Operation Mode Selector Service Indication, OMS-2. Off(00)/ On(01) | 00-01 |
| OMS C3 | Choose Priority of the operation mode selector, OMS-2. The lower the number the higher the priority. | 25-99 |
| OMS C4 | Choose group of the operation mode selector, OMS-2. | 00-10 |
| OMS C5 | Choose display mode of the operation mode selector, OMS-2. Show system mode(00) / Show local mode(01) | 00-01 |
| OMS C6 | Choose Terminal mode of the operation mode selector, OMS-2. The buttons on OMS is disabled(00)/The OMS adapts to system mode(01)/The OMS is setting the operation mode(02) | 00-02 |
| OMS C7 | Mode Selector, Self Service Indication, OMS-2. Off(00)/ On(01) | 00-01 |
| OMS C8 | Mode Selector, Key Impulse, OMS-2.Disabled(00)/Login Required(01) \| Enabled(02) | 00-02 |
| MCU 6F | Choose group of the I/O operation mode selector | 01-10 |
| IOU 97 | Operation Mode Selector Function (I/O unit). Off(00)/ On(01) | 00-01 |
| IOU 9A | Priority of the I/O operation mode selector. | 25-99 |
| IOU 9B | Choose group of the I/O operation mode selector. | 00-10 |


| ELECTROMECHANICAL LOCK parameters |  | Range |
| :--- | :--- | :--- |
| Param. <br> ID | Description | $00-05$ |
| MCU 05 | Lock Configuration (main control). No lock(00)/LDP(01)/LD(02)/ <br> LDP Low Energy(03)/ LD Low Energy(04) / Not to be used(05) |  |
| MCU 06 | Lock Release. Off(00)/ On(01) | $00-01$ |
| MCU 42 | Remain Locked at Stop. Off(00)/ On(01) | $00-01$ |
| MCU 43 | Opening Delay for Lock | $00-99$ sec x 0.1 |
| MCU 44 | Exit Lock. Off(00)/ On(01) | $00-01$ |
| MCU 51 | Push \& Close. Off(00)/ On(01) | $00-01$ |
| MCU 52 | Push \& Close Timeout | $00-99$ sec x10 |
| IOU 98 | Lock Configuration (I/O unit). No lock(00)/LDB(01)/LDE(02)/LDB <br> EMSL(03) | $00-03$ |

## SENSOR parameters

| Param. <br> ID | Description | Range |
| :--- | :--- | :--- |
| MCU 07 | Presence Impulse 1 Configuration. $\mathrm{NO}(00) / \mathrm{NC}(01)$ | $00-01$ |
| MCU 08 | Presence Impulse 2 Configuration. $\mathrm{NO}(00) / \mathrm{NC}(01)$ | $00-01$ |
| MCU 09 | Presence Impulse Monitoring | $00-02$ units |
| MCU 16 | Inner Impulse (motion) Monitoring. Off(00)/ On(01) | $00-01$ |
| MCU 17 | Outer Impulse (motion) Monitoring. Off(00)/ On(01) | $00-01$ |
| MCU 27 | Side Presence Input 1 Configuration. $\mathrm{NO}(00) / \mathrm{NC}(01)$ | $00-01$ |
| MCU 28 | Side Presence Input 2 Configuration. $\mathrm{NO}(00) / \mathrm{NC}(01)$ | $00-01$ |
| MCU 29 | Side Presence Impulse Monitoring | $00-02$ units |
| MCU 30 | Side Presence Activation Distance | $00-99$ dm |
| MCU 31 | Sensor Type. 1-wire(00) / 2-wire(01) Monitoring | $00-01$ |
| MCU 45 | Stop Function. Off(00) / On(01) | $00-01$ |
| MCU 46 | Stop Configuration. NO(00)/NC(01) | $00-01$ |
| MCU 66 | Stop Impulse Monitoring. Off(00)/ On(01) | $00-01$ |
| IOU 91 | Inner impulse 2 monitoring, see page 76 | 03 |
| IOU 93 | Inner impulse 2, see page 76 | 03 |


| TIME parameters |  | Range |
| :--- | :--- | :--- |
| Param. <br> ID | Description | $00-60 \mathrm{sec}$ |
| MCU 03 | Hold Open Time | $00-60 \mathrm{sec}$ |
| MCU 04 | Key Hold Open Time | $00-60 \mathrm{sec}$ |
| MCU 20 | Partial Hold Open Time | $00-60 \mathrm{sec}$ |
| MCU 21 | Push \& Go Hold Open Time | $00-60 \mathrm{sec}$ |
| MCU 22 | Auto Width Activation Time | $00-60 \mathrm{sec}$ |
| MCU 23 | Auto Width Resume Time | $00-10 \mathrm{sec}$ |
| MCU 24 | Jam Hold Time | $00-60 \mathrm{sec}$ |
| MCU 25 | Interlock Disable Time | $00-60 \mathrm{sec}$ |
| MCU 26 | Presence Hold Open Time | $00-60 \mathrm{~min}$ |
| IOU 92 | Open/Close Timeout (I/O unit) |  |


| SPEED parameters |  |  |
| :--- | :--- | :--- |
| Param. <br> ID | Description | Range |
| MCU 00 | High Speed Opening | $10-70 \mathrm{~cm} / \mathrm{sec}$ |
| MCU 01 | Low Speed | $05-70 \mathrm{~cm} / \mathrm{sec}$ |
| MCU 02 | High Speed Closing | $10-70 \mathrm{~cm} / \mathrm{sec}$ |


| POSITION parameters | Range |  |
| :--- | :--- | :--- |
| Param. <br> ID | Description | $00-99 \mathrm{~cm}$ |
| MCU 5C | Pharmacy open 1 position | $00-99 \mathrm{~cm}$ |
| MCU 5D | Pharmacy open 2 position | $00-99 \%$ |
| MCU 11 | Partial Open Position | $00-99 \mathrm{dm}$ |
| MCU 48 | C-Switch Activation Distance | $00-99 \mathrm{~cm}$ |
| MCU 57 | Low Speed Distance, Opening | $00-99 \mathrm{~cm}$ |
| MCU 58 | Low Speed Distance, Closing | $00-99 \mathrm{dm}$ |
| MCU 59 | Open Position | $00-30 \mathrm{~cm}$ |
| MCU 63 | Partial Closed Position |  |

### 13.6 Description of parameters

| Main control board parameters |  |  |  |
| :---: | :---: | :---: | :---: |
| No. | Parameter Name | Value | Description |
| 00 | High Speed Opening |  | Sets the maximum opening speed. Unit cm/s. |
| 01 | Low Speed |  | The low speed is self adjusting to optimal operation if this parameter is set to max. Depending on authority or installation requirements the low speed, low speed distance opening and/or closing can be further reduced. Unit cm/s |
| 02 | High Speed Closing |  | Sets the maximum closing speed. Unit cm/s. |
| 03 | Hold Open Time |  | The general hold open time for Inner and Outer impulses. Unit seconds. |
| 04 | Key Hold Open Time |  | Hold open time for Key impulse. Unit seconds. |
| 05 | Lock Configuration (main control) |  | Europe = Low Energy locks <br> Never LD in escape routes! <br> LDP = locked with power (fail safe) <br> LD = locked without power (fail secure) |
|  | No lock | 00 | No lock |
|  | LDP | 01 | LDP = Locked with power. Only used with US lock or belt lock. |
|  | LD | 02 | LD = Locked without power. Only used with US lock or belt lock. |
|  | LDP LE | 03 | LDP LE = Locked with power low energy. Used with EU lock. |
|  | LD LE | 04 | LD LE = Locked without power low energy. Used with EU lock. |
| 06 | Lock release |  | If "Lock Release" is On, the door will apply force in the closing direction when the lock is unlocking. This is made to prevent a lock from being stuck in locked position when opening. Should be set to On when an electromechanical lock is installed. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 07 | Presence Impulse 1 Configuration |  | This parameter determines if a presence impulse is normally open (NO) or normally closed (NC). |
|  | NO | 00 | Normally open |
|  | NC | 01 | Normally closed |
| 08 | Presence Impulse 2 Configuration |  | This parameter determines if a presence impulse is normally open (NO) or normally closed (NC). |
|  | NO | 00 | Normally open |
|  | NC | 01 | Normally closed |


| Main control board parameters |  |  |  |
| :---: | :---: | :---: | :---: |
| No. | Parameter Name | Value | Description |
| 09 | Presence Impulse Monitoring |  | Presence impulse monitoring is a demand to be activated according to EN 16005 or DIN 18650 if the door travels faster than adjusted according to PRA-0004. |
|  | No monitoring of precense impulse | 00 | Set to " 00 " if no monitoring of Presence impulse sensors is required or if no presence impulse sensors are installed. |
|  | Presence impulse 1 | 01 | Set to " 01 " if one Presence impulse sensor shall be monitored (if only one sensor is used this sensor has to be connected to MCU TB:9, Presence impulse 1). |
|  | Presence impulse 1 and 2 | 02 | Set to " 02 " if two Presence impulse sensors shall be monitored. |
| 10 | Emergency Unit Monitoring |  | The emergency unit will be tested by shutting of the power to the MCU and open the door with the emergency unit. The test is never done in operation mode selection OPEN and normally not in OFF, unless parameter 37 "Emergency Action In OFF Mode" is set to On, see below. <br> Authorities can demand that the emergency unit is monitored on a regular basis, see parameter 40 "Emergency Unit Test Interval" below. Half an hour before this time has elapsed the following outer impulse generates an emergency opening test. If there is no outer impulse within the next half hour, the operator control unit generates the opening impulse by itself ("ghost impulse"). <br> The test is also always performed after a Reset and after changing operation mode selection from a position where a test is not done to a position where the test is made. |
|  | Off | 00 |  |
|  | Convenience Monitoring | 01 | (01) is a simpler one-channel monitoring, this can be done with both MCU and MCU-ER. Convenience monitoring can also be used when monitoring the Convenience battery parameter 38 . It will only indicate empty battery. |
|  | Redundant monitoring | 02 | (02) is a redundant two-channel monitoring that is a demand for escape route according to: EN 16005 or DIN 18650. The redundant two-channel monitoring requires the MCUER control unit. |
| 11 | Partial Open Position | 00-99\% | Sets the "winter opening" size. <br> Note! A building is certified for a certain COW. Depending on how many people that is allowed to be in the specific area there also has to be a certain COW. Partial open position must be set to $80 \%$ of the certified distance in escape routes. Unit\% of COW. |
| 12 | Opening Direction | 00-01 |  |
|  | CW | 00 |  |
|  | CCW | 01 | The tension wheel lock can only work in one opening direction, CW and cannot be used in CCW. |
| 13 | Hold Force | 00-60 N | Adjustment of the force used to keep the door in closed position (ND motor max $30 \mathrm{~N}, \mathrm{HD}$ and DD motor max 60 N ). <br> Unit N . |

## Main control board parameters

| No. | Parameter Name | Value | Description |
| :--- | :--- | :--- | :--- |
| 15 | Run Program | $01-05$ | Performance adjustment. Sets how fast or slow the door <br> shall accelerate or break. |
|  | Smooth | 01 | For light doors. |
| Max Performance | 05 | For heavy doors. |  |
| 16 | Inner Impulse (motion)Monitoring | $00-01$ | According to EN 16005 or DIN 18650 it is a demand to have <br> Inner impulse monitoring = On in escape routes. <br> When inner impulse monitoring is selected C-switch is dis- <br> abled. |
|  | Off | On | Outer Impulse(motion)Monitoring |


| Main control board parameters |  |  | Value | Description |
| :--- | :--- | :--- | :--- | :--- |
| No. | Parameter Name | $00-60$ | Hold open time for Presence impulses 1 \& 2. <br> At least 2 sec to meet ANSI demand. <br> Unit seconds. |  |
| 26 | Presence Hold Open Time | Side |  |  |


| Main control board parameters |  |  |  |
| :---: | :---: | :---: | :---: |
| No. | Parameter Name | Value | Description |
| 31 | Sensor Type | 00-01 | Select type of monitoring for the combined sensors. Choose between 1 -wire ( 00 ) or 2-wire ( 01 ) monitoring. |
|  | 1-wire monitoring | 00 | 1 -wire monitoring is used when combined sensors have only one monitoring input for both presence and impulse field. |
|  | 2-wire monitoring | 01 | 2-wire monitoring is used when a sensor has separate monitoring inputs for both presence and impulse field. If 2 -wire monitoring and inner/outer impulse monitoring are selected, the C-Switch function is switched to inner/outer impulse monitoring (see parameters 16 and 17 on page 83). |
| 32 | Active Brake on Stop | 00-01 |  |
|  | Off | 00 | The door will freewheel until it stops. |
|  | On | 01 | The operator will brake the doors actively during 1 sec . on a Stop impulse. |
| 33 | Push \& Go in EXIT Mode Selection | 00-01 |  |
|  | Off | 00 | Push \& GO is not active in OFF and EXIT mode selection. |
|  | On | 01 | Push \& GO is active in OFF and EXIT mode selection. |
| 34 | Hold Force in EXIT and OFF Mode Selection | 00-01 | With an electromechanical lock this hold force can be unnecessary. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 35 | Toggle Operation Mode Selector after Stop | 00-01 | In operation mode selection OFF the mode must be changed before normal operation after a Stop impulse. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 36 | Emergency Action | 00-01 | Fire closing or Emergency opening. |
|  | Closing | 00 | The door will close on fire impulse or power failure. |
|  | Opening | 01 | The door will open on fire impulse or power failure. |
| 37 | Emergency Action in OFF Mode | 00-01 | Decides if "Emergency Action" shall be performed also in mode selection OFF (= opens also in the middle of the night). |
|  | Off | 00 |  |
|  | On | 01 |  |
| 38 | Convenience battery | 00-01 | When this parameter is set to On (01), with a 24 V (UPS) battery the operator will continue its normal operation in case of mains power failure. Monitoring will be made if parameter 10 is set to Convenience Monitoring (01). Not approved in escape routes! |
|  | Off | 00 |  |
|  | On | 01 |  |


| No. | Parameter Name | Value | Description |
| :---: | :---: | :---: | :---: |
| 39 | Battery Wake-up | 00-01 | The parameter controls how the door is acting on Key impulse or Battery wake up in mode selection OFF without mains power. The parameter "Emergency Action In OFF Mode" (37) must also be set to Off (00). |
|  | Open | 00 | If "Battery Wakeup" is set to Open ( $39=00$ ) the impulse is opening the door fully and stop there. |
|  | Open/Close | 01 | If "Battery Wakeup" is set to Open/Close (01) and parameter "Emergency Action" (36) is set to Opening (01) the impulse is opening the door fully, remains open for the time set by parameter "Key Hold Open Time" (04) and will then close, lock and disconnect the battery. |
| 3A | Lock Door After Fire Closing |  | The parameter sets how the lock will react when a active fire closing impulse is activated. |
|  | Follow Mode Selector | 00 | $\begin{aligned} & \text { SW } \\ & 37 \end{aligned}$ |
|  | Always Unlock | 01 |  |
|  | Always Lock | 02 |  |
| 40 | Emergency Unit Test Interval | 04-23 | The time set in this parameter controls the maximum time until the next automatic test of the emergency unit is performed. <br> Unit hours. |
| 41 | Battery Type | 00-02 | What type of battery that is mounted in the operator is identified during the Learn. |
|  | No battery | 00 |  |
|  | 12V | 01 |  |
|  | 24 V | 02 |  |
| 42 | Remain Locked at Stop | 00-01 | The parameter sets how the lock shall act when Stop impulse is activated (for example break-out). |
|  | Off | 00 | The locked door will be unlocked when Stop impulse is activated. |
|  | On | 01 | The locked door remains locked when Stop impulse is activated. |
| 43 | Opening Delay For Lock | 00-99 | The time the opening is delayed ( $0.0-9.9 \mathrm{sec}$ ) after an opening impulse is given in operation mode selections OFF and EXIT. <br> Unit seconds $\times 0.1$. |
| 44 | Exit Lock | 00-01 | This parameter controls the electro-mechanical lock in the operation mode selector setting EXIT. |
|  | Off | 00 | The electromechanical lock is not locked in EXIT. |
|  | On | 01 | The electromechanical lock is locked in EXIT. |
| 45 | Stop Function | 00-01 | When this parameter is set to On (01) the Stop impulse is enabled, otherwise it is disabled. |
|  | Off | 00 | Stop impulse disabled. |
|  | On | 01 | Stop impulse enabled. |
| 46 | Stop Configuration | 00-01 | Configuration of the Stop impulse. Choose between normally open (NO) or normally closed (NC) Stop impulse. |
|  | NO | 00 | Normally open |
|  | NC | 01 | Normally closed |

## Main control board parameters

| No. | Parameter Name | Value | Description |
| :---: | :---: | :---: | :---: |
| 47 | C-Switch Configuration | 00-01 | Configuration of "C-Switch" (electronic limit switch) output, NO (00) or NC (01). |
|  | NO | 00 | Normally open |
|  | NC | 01 | Normally closed |
| 48 | C-Switch Activation Distance | 00-99 | The C-Switch is an open collector output. The value in the parameter decides how far one door leaf shall travel from closed position before the c-switch change state. Unit dm. |
| 49 | Opening Max Force | 02-23 | The force applied from the operator to the door leaf during opening. See also parameters 50 Closing Max Force, 64 Power Supply Type, and 71 Max Motor Power. <br> The lowest value adjusted in parameters above will be used. Heavy Duty: Max force 190 N. <br> Unit N x10. |
| 4A | Close Kick Force | 02-23 | The force applied from the operator to the door leaf  <br> during the close kick. SW <br> Heavy Duty: Max force 190 N. 3.2 <br> Unit Nx10.  |
| 50 | Closing Max Force | 02-23 | The force applied from the operator to the door leaf during closing. See also parameters 49 Opening Max Force, 64 Power Supply Type, and 71 Max Motor Power. <br> The lowest value adjusted in parameters above will be used. Heavy Duty: Max force 190 N. <br> Unit N x10. |
| 51 | Push \& Close | 00-01 | When this parameter is set to On (01) the motor will in operation mode selections OFF or EXIT try to close the door with the force selected by parameter 50 "Closing Max Force", if someone tries to open it manually. Push \& Close is also known as "poor man's lock". |
|  | Off | 00 |  |
|  | On | 01 |  |
| 52 | Push \& Close Timeout | 00-99 | Adjustable time for how long time the door will continue to "fight back" when someone is trying to force it open. Unit seconds x10. |
| 53 | Operator Type |  |  |
|  | Slider | 00 |  |
| 54 | Service needed Operating Hours | 00-60 | Set time before yellow LED in operation mode selector will start flashing. <br> To clear the service needed indication you have to push both up and down arrow on the MMI at the same time for 5 seconds when the display shows on. After 5 s the display will show SE during another 5 s , release the up and down buttons. While the display shows SE pres Select button and the counters Operating hours and Operating cycles will be set to zero. <br> Unit hour X 1000. |


| Main control board parameters |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| No. | Parameter Name | Value | Description |  |
| 55 | Service Needed Opening Cycles | 00-50 | Set number of openings before yellow LED in operation mode selector will start flashing. <br> To clear the service needed indication you have to push both up and down arrow on the MMI at the same time for 5 seconds when the display shows on. After 5 s the display will show SE during another 5 s, release the up and down buttons. While the display shows SE pres Select button and the counters Operating hours and Operating cycles will be set to zero. <br> Unit cycles X 100.000 . |  |
| 56 | Service Needed Locking Cycles | 00-50 | Set number of lockings before yellow LED in operation mode selector will start flashing. <br> This parameter can not be zeroed by MMI interface. The parameter has to be increased to the next level of service interval. <br> Unit cycles X 10.000 . |  |
| 57 | Low Speed Distance, Opening | 00-99 | "Creep speed" distance during opening. Unit cm. |  |
| 58 | Low Speed Distance, Closing | 00-99 | "Creep speed" distance during closing. Unit cm. |  |
| 59 | Open Position | 00-99 | Opening width of one door leaf. The parameter shall be set automatically by performing a Learn cycle. Unit dm. |  |
| 5C | Pharmacy open 1 position | 00-99 | Lock for pharmacy functionality is not yet available. The door will open the configured distance when a Pharmacy impulse 1 is given. The distance is calculated on one door leaf. <br> This parameter is active when parameter "Pharmacy Function" (9C) is set to On. <br> Unit cm. |  |
| 5D | Pharmacy open 2 position | 00-99 | Lock for pharmacy functionality is not yet available. The door will open the configured distance when a Pharmacy impulse 2 is given. The distance is calculated on one door leaf. <br> This parameter is active when parameter "Pharmacy Function" (9C) is set to On. <br> Unit cm. |  |
| 5E | Status indication | 00-01 | The operator shows the status indication on the LED display of the MCU. See page 75 for more information. |  |
|  | Off | 00 |  |  |
|  | On | 01 |  |  |
| 5F | Default programming | 00-01 | Default programming sets the parameters to the factory default values. | $\begin{aligned} & \text { SW } \\ & 3.2 \end{aligned}$ |
|  | Off | 00 | It is not possible to perform a default programming from the MMI. |  |
|  | On | 01 | It is possible to perform a default programming from the MMI. |  |

## Main control board parameters

| No. | Parameter Name | Value | Description |
| :---: | :---: | :---: | :---: |
| 60 | Learn | 00-01 | Sets the possibility to perform a learn cycle. |
|  | Off | 00 | It is not possible to perform a learn cycle from MMI. |
|  | On | 01 | It is possible to perform a learn cycle from MMI. |
| 61 | Auto Width | 00-01 | If this function is selected (01) and the operation mode selection is AUTO PARTIAL. the door will open from partial open width to full open width, if an opening impulse is given and the door has not closed during the time selected in parameter 22 "Auto Width Activation Time". <br> Must not be used in escape routes. |
|  | Off | 00 | Partial Open. |
|  | On | 01 | Auto Width. |
| 62 | Partial Function | 00-01 | With this function the door can be selected to be partially opened or partially closed (see below 63 "Partial Closed Position"). |
|  | Opened | 00 | Partial Open or Auto Width. |
|  | Closed | 01 | Partial Closed Position, (Auto Airing). |
| 63 | Partial Closed Position | 00-30 | "Partial closed position" (Auto airing function) can be obtained by selecting "Partial Function" (62) Closed (01). An airing position of the door can be set between $0-30 \mathrm{~cm}$ measured from the closed position on one door leaf. The operation mode selector is to be set to AUTO PARTIAL and the closed position of the doors will then be the "Partial Closed Position" . <br> Unit cm. |
| 64 | Power Supply Type | 01-02 | 150 / 75 W power supply. The power supply selected to the operator depends on the desired performance level. See also parameters 49 Opening Max Force, 50 Closing Max Force, and 71 Max Motor Power. <br> The lowest value adjusted in parameters above will be used. |
|  | 150W | 01 |  |
|  | 75W | 02 |  |
| 65 | Sustainable Drive Mode | 00-01 | The electromechanical lock will never lock in Exit mode selection even if parameter 44 is set to $\mathrm{On}(01)$. The (+) 24 V DC to accessories like sensors is turned off when the mode selector is in Off and the door is closed. Motor power is limited to 75 W even if parameter 71 is set to a higher value. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 66 | Stop Impulse Monitoring | 00-01 | Monitoring enables (01) or disables (00) monitoring of the Stop impulse. <br> Stop impulse is not allowed in escape route, unless break out system is used. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 67 | Door Type | 00-01 | To be able to adapt closing speeds according to UL regulation door type has to be selected. |
|  | Single sliding | 00 |  |
|  | Biparting | 01 |  |


| Main control board parameters |  |  |  |
| :---: | :---: | :---: | :---: |
| No. | Parameter Name | Value | Description |
| 68 | Door weight | 01-40 | Will be estimated during the Learn but can also be altered manually. <br> Unit $\mathrm{kg} \times 10$. |
| 69 | Friction | 00-99 | The friction when moving the door is automatically measured during a Learn. The friction for the different performance levels are: <br> Standard not more than 30N. <br> High not more than 50 N . <br> Exceptional not more than 70 N . <br> Unit N. |
| 6A | Interlock Function | 00-01 | Interconnection cable or IOU needed. <br> Maximum cable length 500 m . Length over 30 m , use a straight-through shielded twisted pair (STP/FTP) cable, see page 99 Interlock. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 6b | Synchronizing Function | 00-01 | Interconnection cable needed. <br> Maximum cable length 500 m . Length over 30 m , use a straight-through shielded twisted pair (STP/FTP) cable, see page 100. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 6C | External Bus Device ID | 01-99 | In a chain of interconnected operators one of them has to be the main operator. This operator shall have the value 01 . Up to two operation mode selectors can be connected to the chain of interconnected operators. Both of the operation mode selectors are configured in the main MCU. All other interconnected operators shall have different values in this parameter. This to make every operator unique. |
| 6d | Extended Hold Open Time Function | 00-01 | +5 sec. hold open time on doors often reopening during closing. |
|  | Off | 00 |  |
|  | On | 01 |  |


| Main control board parameters |  |  | Value |
| :--- | :--- | :--- | :--- |
| No. | Description |  |  |
| 6E | MMI access code | $00-01$ | If this parameter is set to single push (00) the parameters <br> are not locked and when set to the four pushes code (01) <br> the possibility to adjust parameters call for a special enabling <br> code (select, learn/exit, learn/exit, select) before altering <br> parameters into the MCU / MCU-ER will be possible. |
|  | One push | Four pushes | 00 |
|  | 01 |  |  |
|  |  | $01-10$ | This parameter groups MCU with OMS. Units with the same <br> value are in the same group. Units in the same group listens <br> to each other. |

## Motor control parameters

| No. | Parameter Name | Value | Description |
| :--- | :--- | :--- | :--- |
| 70 | Motor Type | 01 | Depending on desired performance. |
|  | Heavy Duty | 01 |  |
| 71 | Max Motor Power | $03-15$ | The max amount of power the motor can be supplied with. <br> See also parameters 49 Opening Max Force, 50 Closing Max <br> Force, and 64 Power Supply Type. <br> The lowest value adjusted in parameters above will be used. <br> Unit W $\times 10$. |


| I/O Board parameters |  |  |  |
| :---: | :---: | :---: | :---: |
| No. | Parameter Name | Value | Description |
| 90 | Function Select IOU-TB:3 | 00-03 |  |
|  | No function | 00 |  |
|  | Nurse function | 01 | The door will open to partial opening in operation mode selections EXIT, AUTO and AUTO PARTIAL. |
|  | LDE up | 02 | Espagnolette lock. Sets input to LDE lock up. |
|  | Interlock out | 03 | When configuring for interlock also set parameter 6A = 01 |
| 91 | Function Select IOU-TB:4 | 00-04 |  |
|  | No function | 00 |  |
|  | Open/Close Function | 01 | One impulse opens the door the next impulse closes the door. Available in OMS mode EXIT, AUTO, PARTIAL. |
|  | Interlock disable function | 02 | Disables interlock, both doors can be open at the same time. |
|  | Inner impulse 2 monitoring | 03 | Sets inner impulse 2 monitoring for the second inner impulse on the IO unit. Set also parameter $93=3$. |
|  | Interlock in | 04 | When configuring for interlock also set parameter 6 A $=01$. |
| 92 | Open/Close Timeout | 00-60 | The time set in this parameter controls when a door shall start closing automatically if left open by an Open/Close impulse. $00 \mathrm{~min}=$ no automatic closing. <br> Unit minutes. |
| 93 | Function Select IOU-TB:2 | 00-03 |  |
|  | No function | 00 |  |
|  | Close function | 01 | Close impulse is selected. This impulse will immediately close the door, even during opening, and remain closed as long as the Close impulse is active. The electro-mechanical lock will lock the closed door. <br> May not be used on an escape route door. |
|  | LDE down | 02 | Espagnolette lock. Sets input to LDE lock down. |
|  | Inner impulse 2 | 03 | When two inner impulses are to be used. Sets input to inner impulse 2. |
| 94 | Fire Impulse Function | 00-01 | Depending on configuration in Emergency Action (36), the door will open or close on fire impulse. <br> Fire impulse override presence impulse. <br> At closing, the door will not reopen on jam. |
|  | Off | 00 | Fire impulse disabled. |
|  | On | 01 | Fire impulse enabled. |
| 95 | Emergency Open Impulse Function | 00-01 | Fireman's opening. |
|  | Off | 00 |  |
|  | On | 01 |  |
| 96 | Emergency Open Impulse Configuration | 00-01 | Configures the button used for Fireman's opening. |
|  | NO | 00 | Normally open |
|  | NC | 01 | Normally closed |
| 97 | Operation Mode Selector Function | 00-01 | Switch / timer / relay /"old" operation mode selector (5-wire). |
|  | Off | 00 |  |
|  | On | 01 | Not allowed in escape route, according to EN 16005 and DIN 18650. |

I/O Board parameters

| No. | Parameter Name | Value | Description |
| :---: | :---: | :---: | :---: |
| 98 | Lock Configuration | 00-03 | LDB = locked with power and bistable, LDE = espagnolette lock. |
|  | No lock | 00 | No lock |
|  | Bi-stable lock | 01 | LDB = locked with power and bistable |
|  | Espagnolette lock | 02 | LDE = espagnolette lock |
|  | Bi-stable lock EMSL | 03 | LDB $=$ locked with power and bistable |
| 99 | Function Select IOU-TB:6 |  | Possibility to disable Sustainable drive mode or to enable Mode Selector with this function through IOUтв:6. |
|  | No function | 00 |  |
|  | Sustainable Disable | 01 | Disables Sustainable drive mode. <br> It is possible to disable sustainable drive mode. As long as TB:6 is active the operator will run with full power. |
|  | Mode Selector Enable | 02 | Enable the Mode Selector with an external key. IOU mode selector and PS-6 are not affected by this parameter. <br> When parameter is set to value 02 the OMS is locked. If an impulse is given on IOU TB: 6 the indication LED on OMS will be steady red during 15 seconds and it is possible to change mode selection (set parameter $b 1 / C 1=00$ ). |
| 9A | Priority of the I/O operation mode selector | 25-99 | The lower the number is the higher the priority. |
| 9B | Choose group of the I/O operation mode selector | 00-10 | This controls which MCU that looks at which OMS. It is possible to group different OMS to different MCU. MCU and OMS with same group number listens to each other. If value 00 is selected the IOU mode selector controls all operators. |
| 9C | Pharmacy function | 00-01 | Lock for pharmacy functionality is not yet available. |
|  | Off | 00 |  |
|  | On | 01 |  |

Escape route parameters

| No. | Parameter Name | Value | Description |
| :--- | :--- | :--- | :--- |
| A0 | Escape Route Motor Configuration | $01-02$ | Single motor or double motor depending on authority de- <br> mand. |
|  | 1-motor | 01 |  |
|  | 2-motor | 02 |  |


| Operation mode selector parameters |  |  |  |
| :---: | :---: | :---: | :---: |
| No. | Parameter Name | Value | Description |
| b0 | Operation Mode Selector Variant, OMS-1 | 01-04 | Europe $=5$ buttons (04). |
|  | 3 buttons with EXIT | 01 |  |
|  | 3 buttons with AUTO | 02 |  |
|  | 4 buttons | 03 |  |
|  | 5 buttons | 04 |  |
| b1 | Operation Mode Selector Key Lock, OMS-1 | 00-02 | There are three different levels of access code choices for the operation mode selector: |
|  | Off | 00 | No access code. |
|  | Hold for two sec | 01 | Access is obtained by pushing an arrow symbol pointing up or down for 2 seconds. |
|  | Passcode | 02 | An optional passcode can be selected where the access is obtained by briefly pushing in turn the arrow up symbol, followed by the arrow down symbol, followed by the arrow down symbol again and at last the arrow up. The entire code must be entered within 3 seconds. <br> Pass code $={ }^{\mathrm{E}} \mathrm{MM}^{\mathrm{E}}$. |
| b2 | Operation Mode Selector Service Indication, OMS-1 | 00-01 | Yellow flashing service LED. <br> Service indication on operation mode selector. <br> No service indication (00). <br> Indicate service (01). |
|  | Off | 00 |  |
|  | On | 01 |  |
| b3 | Choose Priority of the operation mode selector, OMS-1 | 25-99 | The lower the number the higher the priority. |
| b4 | Choose group of the operation mode selector, OMS-1 | 00-10 | This controls which MCU that looks at which OMS. It is possible to group different OMS to different MCU. MCU and OMS with same group number listens to each other. If a OMS is set to 0 this OMS controls all operators that is connected in that loop. |
| b5 | Choose display mode of the operation mode selector, OMS-1. | 00-01 | In Show local mode the OMS shows the last setting made on the OMS. <br> In Show system mode the OMS shows the setting that the operator is put to. It is shown with one flach every 5 s . When the OMS is flashing every 5 sit is not possible to change the mode on the OMS. |
|  | Show system mode | 00 |  |
|  | Show local mode | 01 |  |
| b6 | Choose Terminal mode of the operation mode selector, OMS-1 | 00-02 |  |
|  | The buttons on OMS are disabled | 00 |  |
|  | The OMS-1 adapts to system mode | 01 |  |
|  | The OMS-1 keeps its selected mode. | 02 |  |

Operation mode selector parameters

| No. | Parameter Name | Value | Description |  |
| :---: | :---: | :---: | :---: | :---: |
| b7 | Mode Selector, Self Service Indication, OMS-1 | 00-01 | Orange flashing service LED. <br> Self service indication on operation mode selector. | $\begin{aligned} & \text { SW } \\ & 3.2 \end{aligned}$ |
|  | Off | 00 | No self service indication. |  |
|  | On | 01 | Indicate self service. |  |
| b8 | Mode Selector Key Impulse, OMS-1 | 00-02 | Key impulse to the operator can be made in the following ways by pushing the symbol below. <br> OMS Basic - | $\begin{aligned} & \text { SW } \\ & 3.2 \end{aligned}$ |
|  | Disabled | 00 | Disables the possibility to give key impulse. |  |
|  | Login Required | 01 | Login required on the OMS to enable the possibility to give key impulse. <br> The login is configured through parameter 99 and b1. |  |
|  | Enabled | 02 | Enables the possibility to always give key impulse. |  |
| C0 | Operation Mode Selector Variant, OMS-2 | 01-04 | Europe $=5$ buttons(04). |  |
|  | 3 buttons with EXIT | 01 |  |  |
|  | 3 buttons with AUTO | 02 |  |  |
|  | 4 buttons | 03 |  |  |
|  | 5 buttons | 04 |  |  |
| C1 | Operation Mode Selector Key Lock, OMS-2 | 00-02 | There are three different levels of access code choices for the operation mode selector: |  |
|  | Off | 00 | No access code. |  |
|  | Hold for two sec | 01 | Access is obtained by pushing an arrow symbol pointing up or down for 2 seconds. |  |
|  | Passcode | 02 | An optional passcode can be selected where the access is obtained by briefly pushing in turn the arrow up symbol, followed by the arrow down symbol, followed by the arrow down symbol again and at last the arrow up. The entire code must be entered within 3 seconds.$\text { Pass code }=\mathrm{E}_{\mathrm{MM}^{\mathrm{E}}} \text {. }$ |  |
| C2 | Operation Mode Selector Service Indication, OMS-2 | 00-01 | Yellow flashing service LED. <br> Service indication on operation mode selector. <br> No service indication (00). <br> Indicate service (01). |  |
|  | Off | 00 |  |  |
|  | On | 01 |  |  |
| C3 | Choose Priority of the operation mode selector, OMS-2 | 25-99 | Selectable between 25-99 <br> The lower the number the higher the priority. |  |
| C4 | Choose group of the operation mode selector, OMS-2 | 00-10 | Selectable between 00-10 <br> This controls which MCU that looks at which OMS. It is sible to group different OMS to different MCU. MCU and OMS with same group number listens to each If a OMS is set to 0 this OMS controls all operators that connected in that loop. | pos- <br> ther. is |


| Operation mode selector parameters |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| $\begin{array}{\|l\|} \hline \text { No. } \\ \hline \text { C5 } \\ \hline \end{array}$ | Parameter Name | Value | Description |  |
|  | Choose display mode of the operation mode selector, OMS-2. | 00-01 | In Show local mode the OMS shows the last setting made on the OMS. <br> In Show system mode the OMS shows the setting that the operator is put to. It is shown with one flach every 5 s . When the OMS is flashing every 5 sit is not possible to change the mode on the OMS. |  |
|  | Show system mode | 00 |  |  |
|  | Show local mode | 01 |  |  |
| C6 | Choose Terminal mode of the operation mode selector, OMS-2 | 00-02 |  |  |
|  | The buttons on OMS-2 are disabled | 00 |  |  |
|  | The OMS-2 adapts to system mode | 01 |  |  |
|  | The OMS-2 keeps its selected mode. | 02 |  |  |
| C7 | Mode Selector, Self Service Indication, OMS-2 | 00-01 | Orange flashing service LED. | $\begin{aligned} & \text { SW } \\ & 3.2 \end{aligned}$ |
|  | Off | 00 | No self service indication. |  |
|  | On | 01 | Indicate self service. |  |
| C8 | Mode Selector Key Impulse, OMS-2 | 00-02 | Key impulse to the operator can be made in the following ways by pushing the symbol below. <br> OMS Basic - | $\begin{aligned} & \text { SW } \\ & 3.2 \end{aligned}$ |
|  | Disabled | 00 | Disables the possibility to give key impulse. |  |
|  | Login Required | 01 | Login required on the OMS to enable the possibility to give key impulse. <br> The login is configured through parameter 99 and b1. |  |
|  | Enabled | 02 | Enables the possibility to always give key impulse. |  |

## 14 Signage



Check that all required signage is applied and intact. Mandatory indicates that the signage is required by European directives and equivalent national legislation outside the European Union.

| (A) | Product label: Mandatory |
| :---: | :---: |
| (B) | Emergency break-out: Mandatory, if approved for escape route. |
| (c) | Entrematic Nordic door sticker:Mandatory according to Entrematic Nordic brand instructions, European directives and equivalent national legislation outside the European Union, to highlight the presence of the glass. |
| (D) | Supervision of child (applied to both sides of the door): Mandatory according to national regulations. Recommended, if the risk analysis shows use by children. |
| (E) | Operator designed for disabled people: Recommended, if applicable (applied to both sides of the door). |
| © | Activation by disabled people: Recommended, if applicable. |
| (G) | No entry, identifying one-way traffic: Mandatory in GB and US, if applicable, not included in the product. |
| (H) | Local product label |
| (1) | Keep clear |
| ® | Automatic door |

## 15 Accessories

15.1 Interconnection of operators
15.1.1 Interconnection cable

Interconnection cable is used for controlling several operators with one or more operation mode selectors (OMS) and for interlocking or synchronization.

Operators can communicate with each other by connecting an interconnection cable between the operators.

Cable connection:


Pin 1 to pin 1
.....
.....
Pin 8 to pin 8


### 15.1.2 Hardware configuration for interconnection

When interconnecting more than two units (MCU and/or operation mode selectors (OMS)) to the external bus, only the two end units must be terminated. To make this, the jumper JMP shall be removed from the middle $\operatorname{MCU}(\mathrm{s})$. When the jumper is removed the termination is removed. Maximum 2 MCU can be interconnected together with 1 OMS.


Total maximum cable length is 500 m .
Use a straight-through shielded twisted pair (STP/FTP) CAT5/CAT5e cable if the length exceeds 30 m or is in electrically disturbing environment.
15.1.3 Parameter configuration for interconnection

Note! Do not connect any operation mode selector (OMS) before the configuration of 6C is done on all MCUs.

One of the operators has to be the main MCU (MCU-1). The main MCU shall have the value 01 in parameter 6C. All the other interconnected operators shall have ascending values in parameter 6 C. When the configuration is done break the power on all the interconnected operators. Connect all OMS, turn on the power. The main MCU is the control unit that holds the parameters to the operation mode selectors (OMS-1, OMS-2).
15.2 Interlock

When operators are interlocked only one door can open at the time. The open door must close before the other door can open. For instance from the start: both doors are closed. If door 1 gets an impulse this door opens. If door 2 also gets an impulse before door 1 has closed, door 2 will stay
closed. When door 1 has closed door 2 will open. It is not necessary for door 2 to get another impulse for the door to open, the first impulse is remembered and will open the door. A typical use of this function is an air lock to reduce draft and energy loss in an entrances. It is not used for security reason.


The following alternative is how to make an interlocking.
1 Interlock the operator through the IOU, this is compatible with EMSL interlock. It is possible to interlock many operators. Set the following parameters in all MCUs:
6 A = 01 Interlock function
$90=03$ Interlock out
$91=04$ Interlock in
Connect the IOU according to the picture below.


### 15.3 Synchronization

Synchronization is when two operators work together. The doors opens and closes at the same time. A typical use is when two big single sliders are put together to get one big clear opening width. Synchronized can only be done between two operators, not more.

See chapter 15.1.1, 15.1.2 and 15.1.3 on how to connect the operators together, interconnection of operators, and follow the instruction.
For synchronization set parameter $6 \mathrm{~b}=01$ on all MCUs.
Make a reset after adjustment.

For further configuration examples about operation mode selector (OMS), see page 101.

15.4 Operation mode selectors (OMS)
15.4.1 Types

For the mode selector there are a couple of alternatives:

- OMS Basic, a narrow version, WxH 44x80 mm with 5 selections.
- OMS Basic, two square versions, WxH $80 \times 80$ or $55 \times 55 \mathrm{~mm}$ with 5 selections.
- PS-6, a 2-wire analog mode selector connected to the MCU.

The operation mode selectors (OMS Basic) can be flush mounted in profiles or in electrical wall boxes. The operation mode selectors (OMS Basic) can also be installed surface applied in wall boxes.

Note! Do not use PS-6 in combination with operation mode selector (OMS).
If PS-6 is used together with an IOU it is necessary to set parameter $97=00$ to disable IOU mode selector.

PS-6 cannot be used in an interconnected system.
Only one PS-6 can be connected to the MCU.

| Surface mounted OMS Basic $44 \times 80 \mathrm{~mm}$ | Flush mounted OMS Basic $44 \times 80 \mathrm{~mm}$ |
| :---: | :---: |
|  |  |
| Flush mounted OMS Basic $80 \times 80 \mathrm{~mm}$ | Flush mounted OMS Basic $55 \times 55 \mathrm{~mm}$ |
|  |  |
| Surface mounted PS-6 |  |
|  |  |

15.4.2 Operation mode selector (OMS) functionality

Check how to install interconnected units before configuring the operation mode selector(OMS). See section 15.1.1 on page 98.
All functionality is programmed through the MMI on the main MCU-1 (has parameter $6 \mathrm{C}=01$ ).
There are mainly three (3) different types of configurations for MCU and OMS. But there are a lot of different choices and combinations that are possible. The most common options are listed below.

The "configure parameter" shows which parameter to change from the default setting to obtain the function described, the parameters in the parenthesis shall represent the default values.

## Grouping operators

When connecting several MCU together they might need to be grouped together.MCUs are grouped by entering the same value in the group parameter, MCU 6F, IOU 9B, OMS-1 B4, OMS-2 C4. The units that are grouped together will operate together. If OMS or IOU has the value 00 in the group parameter these units will control all interconnected MCUs regardless of group value.

## Priority of operation mode selectors (OMS)

The priority of the operation mode selectors (OMS) determine which operation mode selector (OMS) that shall decide the mode selection on the MCU. The lower the number is in parameter Priority of the mode selector the higher priority it has.
If two mode selectors have the same value in Parameter Priority, the mode selector pushed last is the one that will control the MCU.

| 1 | Single control  <br>  MCU <br>   <br> OMS-1  |  | One MCU and one OMS-1. MCU is controlled by the OMS-1. <br> No configuration needed. <br> Configure parameter MCU, b5 $=0, \mathrm{~b} 6=1(6 \mathrm{~F}=01, \mathrm{~b} 3=40, \mathrm{~b} 4=01)$. |
| :---: | :---: | :---: | :---: |
| 2 |  |  | One MCU with IOU and one OMS-1. <br> OMS-1 controls MCU when IOU is in AUTO. <br> When IOU is not in AUTO, IOU controls MCU and OMS- 1 shows active mode selection. <br> OMS- 1 is flashing once every 5 second to show that it is remotely overridden. When the OMS- 1 is remotely overridden it is not possible to change its mode. <br> Configure parameter MCU, $\mathrm{b} 5=0, \mathrm{~b} 6=1(6 \mathrm{~F}=01,97=01,9 \mathrm{~A}=30,9 \mathrm{~b}=$ $01, b 3=40, b 4=01$ ). |
| 3 | Local paired, | control with I/O unit override <br> CU-2 <br> or | Two MCU, one OMS-1 and one IOU connected to MCU-1. OMS-1 controls MCU- 1 and MCU- 2 when IOU is in AUTO. When IOU is not in AUTO, IOU controls both MCU-1 and MCU-2. OMS-1 is flashing once every 5 second to show that it is remotely overridden. When the OMS-1 is remotely overridden it is not possible to change its mode. <br> Configure parameter MCU-1, $\mathrm{b} 5=0, \mathrm{~b} 6=1(6 \mathrm{C}=1,6 \mathrm{~F}=01,97=01$, $9 A=30,9 b=1, b 3=40, b 4=01$ ). <br> Configure parameter MCU-2 6C=2, (6F=1). |

Operation of operation mode selector (OMS)


The different operation modes are selected by pushing the arrow symbols pointing upwards or downwards. When a button is pushed a buzzer will sound. The present selection is indicated by a blue light to the left of the function symbol.
When an arrow symbol has not been pushed for 5 seconds the access will be locked.
In the upper right corner a flashing light can be displayed.

- A red light every other second indicates an error in the door operator MCU. If the error remains after a RESET a service visit is required. See also page 121.
- If the red light is quickly flashing 4 times per second it is indicating an internal error in the operation mode selector (OMS).
- An orange light every other second is indicating a status or condition that can be cleared by the owner e.g. a break-out door is standing open.
- A yellow light every other second is indicating that maintenance is due.

The operation mode selectors are available with 5 selections (plus RESET).
With 5 selections OPEN, AUTO PARTIAL, AUTO, EXIT and OFF functions can be obtained.


| Symbol | Text | Function |
| :--- | :--- | :--- |
| OPEN | The door is permanently open. The door can be moved by hand e.g. <br> for window cleaning. All activation units except for the emergency <br> push button (if fitted) are disconnected. |  |
| AUTO | Two-way traffic, AUTO PARTIAL is obtained. The door can be opened <br> partially with the inner and outer activation units and with a key <br> switch (if fitted). With an emergency push-button the door opens <br> fully. |  |
| EXIT | Two-way traffic, normal operation of the door. The door can be <br> opened with the inner and outer activation units and with a key <br> switch/emergency push-button (if fitted). |  |
| Passage from inside only. The door is normally locked if an elec- <br> tromechanical locking device has been fitted. The door can only be <br> opened with the inner activation unit or with a key switch/emergency <br> push-button (if fitted). |  |  |
| OF | This function is only used on emergency escape doors after it is cer- <br> tain that all people have left the building. <br> The door cannot be opened with inner or outer activation units. The <br> door is locked if an electromechanical locking device has been fitted. <br> The door can be opened partially with a key switch (if fitted). The <br> door can be opened fully with an emergency pushbutton (iff fitted). <br> The door can also be opened partially from the operation mode se- <br> lector ifthe arrow down button is held for 2 seconds. No access code <br> is necessary for this and the key impulse is indicated by briefly <br> showing a blue light to the left of the OPEN symbol and then a <br> flashing blue light to the left of the OFF symbol for another 15 <br> seconds. |  |
| RESET | By briefly pushing the dot, placed in the lower right corner of the <br> operation mode selector, with a narrow object, the door operator <br> will make a RESET function with a system test. The door will then be <br> ready for normal operation. |  |

### 15.5 Replacement of secondary track

15.5.1 Shortening of secondary track

It is necessary to adapt the secondary track according to the door size in each installation according to the instructions that follows.

15.5.2 Shortening the bar
$X=A-(2 \times$ TDW - LAP -300$) \mathrm{mm}$

15.5.3 Shortening the L-profile

Note! The L-profile will only be delivered when the door width is more than 730 mm .
$X=A$ - (TDW - LAP -445 ) mm

15.5.4 Shortening the shim
$\longrightarrow \mathrm{X}=\mathrm{A}-(2 \times$ TDW - LAP -34$) \mathrm{mm}$

15.5.5 Shortening the tube

$\longrightarrow$ P $\sim$ - (TDW - LAP -7 ) mm

15.5.6 Shortening and creating new holes in the secondary track
B 28 mm (when using short wheel holder)
B 48 mm (when using normal wheel holder)
$\mathrm{C}=28 \mathrm{~mm}$ (when using short wheel holder)
$\mathrm{C}=48 \mathrm{~mm}$ (when using normal wheel holder)
$\varnothing 4,52$ new holes
$X=A-(2 \times$ TDW - LAP -34$) \mathrm{mm}$

Left opening door leaf, EM Slim


Right opening door leaf, EM Slim

15.5.7 Assemble the secondary track

The following illustrations show the secondary track for left opening door. Insert the bar into the tube.


Place the secondary track on the tube with the shim inbetween. Insert the end cap.


Place two door holders and attach them with screws.
Note! The middle door holder shall be placed as centered as possible over the end of the tube.


Place the L-profile and attach it with screws, placed in every other hole starting from both ends.
Note! Never leave two holes next to each other empty.
Note! The L-profile will only be delivered when the door width (TDW) is more than 730 mm .


Slide the plastic cover onto the bar, until it reaches the tube.
Note! The plastic cover shall cover the gap over the leading edge of the slow moving door in the EM Slim system. In any other system it shall be removed.


Attach the trailing door holder with screws loosely to the short bar.


Attach the track to the bar with the screws loosely.


Add the plastic track and attach it with one screw in the trailing edge.
Attach two screws as door stops.


Mount the secondary track according to page 31.
15.6 Lock

## Electromechanical lock

The following locks are available to the operator:

- Locked with power (LDP), fail safe
- Locked without power (LD), fail secure
- Bistable lock (LDB)

Note! The espagnolette lock is at the moment not allowed to mount in escape routs.
15.6.1 Mounting the lock

## Lock kit

| Part | Part description | Single | Bi-parting |
| :---: | :---: | :---: | :---: |
|  | Lock | x 1 | x 1 |
|  | Telescopic ramp kit | x 1 |  |
| 0 (5) | Telescopic ramp kit |  | x 1 |
| 8 | Screw | x 1 | x 2 |
| 孚路 | Adjustment washer | x 1 | x 1 |
|  | U-plate | x 1 | x 1 |
|  | Spring latch | x 2 | x 4 |
| Oas | Spring latch, short | x 2 | x 4 |



Figure 2: Switch to short spring latch

## For single sliding doors

Note! The hook (3) shall reinforce the lock for single sliders. To be able to fit the hook under the lock the track needs to be removed.
a Push the doors to closed position.
b Put the lock (2) in place for measurement on where to cut the plastic track (1).
C On the opposite side of the door, under the lock (2), cut and take out the plastic track (1) with a length of $3 / 4$ of the width of the lock.
d Put the hook (3) on the support beam where the plastic track (1) has been cut off.
e Mount the lock (2) over the hook (3) and tighten the two outer screws (4).
$f$ When the lock (2) is in the right position, tighten the mid screw.


1 Plastic track
2 Lock
3 Hook (only for single doors)
4 Screw

## For bi-parting doors

a If needed, adjust the wheel holders (5) on the fast moving door so the spring latch (6) has a good grip in the lock, see page 33.
b The spring latch (6) shall be mounted with a distance of 2-4 mm from the lock body. Use the washers (7) to depth adjust the spring latches to the right distance.


Note! Washers (7) not used between the spring latch and the wheel holder must be placed between the spring latch (6) and the screw (8), otherwise the screw will interfere with the wheels inside the wheel holder.


Figure 3: Maximum depth adjustment


Figure 4: Minimum depth adjustment
1 Wheel holder
3 Washer
2 Spring latch
4 Screw
c Push the doors to closed position. Place the lock (2) over the plastic track (1) in the beam at the leading edge of the doors. Tighten the screws (4) gently.
d Mount the telescopic ramp kit.

e Adjust the plastic ramps (9) so they are centered in the spring latches (6).
$f$ Make sure the lock (2) is centered between the doors by locking the lock (2) and pulling the doors apart.
g Tighten the screws (4) and the middle screw (10).


1 Plastic track
2 Lock
4 Screw
6 Spring latch
9 Plastic ramp for fast moving door

10 Middle screw

## Connection

Big coil on LD, LDP, LDB, connects to;
Black to MCU:18
Black to MCU:19

Bi-stable lock small coil;
Blue to IOU:16
Gray to IOU:17
15.7 Cover

Made in clear anodized aluminium as standard. Paint finished in RAL colours or anodizing optional.
15.8 Motion sensor and presence sensors

Motion and presence sensors, see separate manuals or installation drawings on pages 67, 68 and 69.
15.9 Manual Opening Lock device, MOLD

For manual unlocking of the electrical lock (LD), locked without power (fail safe).


See separate installation drawing 1013736.
15.10 Limit switch kit, LSK

For more information, see installation drawing 1013640.


1 Activator
2 Holder
3 Micro Switch
4 Screw
15.11 Lock indication switch, LIS

For more information, see installation drawing 1013640.


1 Lockindication switch(LIS)
2 Lock
15.12 Locked door indicator, LDI

For indication of locked lock and closed door for connection to alarm system.
See separate installation drawing 1013640.


1 Holder
2 Screw
3 Magnetic switch
4 Magnet
5 Activator

### 15.13 Quick connectors

15.13.1 $2 \times 10$ to $1 \times 10$ converter

See separate installation drawing 1016751 for how to
1 Connect 2 monitored inner impulses
2 Connect 2 inner impulses, inner impulse shall not be monitored
3 Connect 2 monitored outer impulses
4 Connect 2 outer impulses, outer impulse shall not be monitored
15.13.2 8 to 10 converter

Convert side presence sensor(s) to presence impulse(s).
Combine 8 to 10 and $2 \times 10$ to $1 \times 10$ converters to allow $1-4$ sensors to be converted from side presence to presence impulse.


| Parameter No. | Value |
| :--- | :--- |
| 07 | $00(\mathrm{NO})$ or $01(\mathrm{NC})$ |
| 08 | $00(\mathrm{NO})$ or $01(\mathrm{NC})$ |
| 09 | 01 one side, 02 two sides |

### 15.14 Cover latch, alternative

The alternative cover latch is available as a spare part, 330000480 (one piece).


### 15.15 Electrical emergency unit with batteries

Used if a door is required to be opened or closed by means of a rechargeable battery unit and remain in this position in the event of power failure. Authorities can demand that the emergency units are monitored on a regular time basis. Half an hour before this time has elapsed the following opening impulse generates an emergency opening test. If there is no opening impulse within the next half hour, the operator control unit generates the opening impulse itself.
If the battery opens the door within the limited time the test is successful and the door resumes the function set by the operation mode selector.

Note! The test is never performed in operation mode selection OPEN. In OFF mode it can be selected. The test is always performed after a RESET and after changing operation mode selection, from a position where a test is not done to a position where the test is a demand.

### 15.16 Electrical emergency unit with batteries and two motors

Used if a door is required to be opened by means of a rechargeable battery unit and remain in this position in the event of power failure. Authorities can demand that the emergency unit is monitored on a regular time basis. Half an hour before this time has elapsed the following opening impulse generates an emergency opening test. If there is no opening impulse within half an hour, the operator control unit generates the opening impulse itself.
If the battery opens the door within the limited time the test is successful and the door resumes the function set by the operation mode selector.

Note! The test is never performed in operation mode selector setting OPEN. In setting OFF it can be selected. The test is always performed after a RESET and after changing operation mode selection, from a position where a test is not done to a position where the test is a demand.
15.17 Emergency closing with repeated closing

If the door is opened by hand after an electrical emergency closing, it will close again.
15.18 Break-out unit PSB

Enables door/side screens to be broken outwards in case of emergency.
See page 14 and separate installation drawing 1003658.
15.19 Convenience battery UPS

Stand-by supply which gives continued operation during short power failure.
24 V Battery is required.
15.20 External error indication

Obtained if a lamp or a buzzer is connected. IOU required.
15.21 Key switches (flush and/or surface mounted)

Used to give opening impulse to the door in any operation mode selector setting. The key switch can also open the door when power is switched off, if a battery is fitted.
15.22 Push button

Used to give opening impulse to the door.
See separate installation drawing 656005.
15.23 Upgrades

Exceptional performance:

- Install 150 W power supply

Escape route according to EN16005 and DIN 18650:

## Requires:

MCU-ER board and 24 V battery. Monitored presence sensors, and inner impulse monitoring. Only 1 OMS is allowed.

For DIN 18650 countries also Double motor.

## Configure parameters:

$9=2$ Monitored presence impulse
$10=2$ Monitored emergency unit
$11=$ Partial open position must be set to $80 \%$ of the certified distance in escape routes.
$16=1$ Monitored inner impulse
$29=2$ If applicable Monitored side presence impulse
$30=$ calculate the distance to $80 \%$ of COW. Side presence activation distance.
$40=23$ hours
$44=0$ The electromechanical lock is not locked in EXIT.
$45=0$ Stop Function disabled, if door system is other than break-out.
$97=0$ Operation Mode Selector Function (I/O unit) disabled.
b1 = 2 Passcode or b1 = 3 Key
For DIN 18650 countries also A0 $=2$

## Extra functionality that requires an I/O-unit (IOU):

15.24 Open / Close function

One button impulse, will alternate between Open and Close. The door will stand open until next impulse or can after an adjustable time delay automatically start to close even if a new impulse is not received.
15.25 Fire alarm connection

Used to emergency open or fire close the door with mains power on.

### 15.26 Nurse function

Used mostly in combination as a Nurse - Bed function. Nurse opens the door to partial open position, and bed (connected to inner or outer impulse) opens to full open position.

Nurse works in operation mode selections Exit, Auto.
The Nurse impulse has the same hold open time as partial open.
15.27 Remote Exit mode

Remotely put door into Exit via an remote system, like timer. Requires a N/O contact.
15.28 Emergency open impulse

Used to give opening (fireman's opening) impulse to the door in any operation mode selector setting. With electrical emergency unit also during power failure.

## 16 Troubleshooting

Before starting the troubleshooting, check that the operation mode is correctly selected. Start the troubleshooting by checking the mechanical and electrical parts of the operator in the order listed below.

The electromechanical parts are fixed in the support beam. To replace these components, the complete unit has to be loosened and replaced.
a The main control unit is equipped with a two digit display for error indication.

- During normal operation the display shows 'on'.
- If all segments are off in the display check the mains power, power supply cable or perform a RESET. If the problem remains replace the main control unit or the power supply.
- When an error is active the display is alternating between an error type e.g. E4 (Motor / Encoder Error) and a second two digit number specifying the error more in detail e.g. 03 (encoder error). If several errors are active they will be displayed in sequence. On each electronic unit there is also a green light emitting diode (LED). If the LED is off or flashing it is indicating that this unit is failing.


1 Up (to step up in parameter or value menu)
2 Select (enters into parameter or value menu and program a value into memory)
3 Down (to step down in parameter or value menu)
4 Learn/Exit (Learn has 3 functions, 1 quick learn, 2 Normal learn, 3 default setting, Exit jumps out from value menu without saving or parameter menu)
b Disconnect the mains power and batteries, if fitted. Unlock all mechanical locks. Pull the door leaf manually and check that the door can be easily moved over the complete sliding track/floor guide. If the door leaf stops or is hard to move, the reason may be sand, stones, rubbish etc. in the floor guide.
The door leaf may also be jamming on the floor or on the weather proofing brush strips. Clean the floor guide, adjust the door leaf height/depth or take other necessary measures e.g. replacement of worn parts until the door leaf is running smoothly when manually operated.
c If the belt is making noise against the beam or cover check that there is the right belt tension. On the Tension wheel assembly, measure the distance between the adjustment screw and the nut. The distance shall be 47 mm . Remove the slack reducers and release the fixing nut in the center of the tension wheel and check that the distance is $1-2 \mathrm{~mm}$ between the nut and the adjacent plate.


| Main error: Power Supply |  |  |
| :--- | :--- | :--- |
| Detailed error | Reason | Remedy |
| -- | There is not enough power to the MCU. | Check that the power does not drop from the PSU, <br> check cables. |
| Not enough power |  | Replace the PSU. |


| Main error: E1 Sensor Error |  |  |
| :---: | :---: | :---: |
| Detailed error | Reason | Remedy |
| 19 Inner Impulse Error | The control unit does not get a test answer from the activation unit. | Make sure that the monitoring output is connected and the connections are OK. |
|  |  | Replace the monitored inner activation unit. |
| 20 Fire Impulse Error | The control unit does not get a test answer from the fire alarm. | Make sure that the fire alarm connections are OK. |
| 28 <br> IOU Inner impulse 2 error | The control unit does not get a test answer from the activation unit. | Make sure that the monitoring output is connected and the connections are OK. |
|  |  | Replace the monitored inner activation unit. |
| 29 <br> Outer Impulse Error | The control unit does not get a test answer from the activation unit. | Make sure that the monitoring output is connected and the connections are OK. |
|  |  | Replace the monitored outer activation unit. |
| 30 <br> Stop Impulse Error | The control unit does not get a test answer from the stop impulse. | Make sure that the monitoring output is connected and the connections are OK. |
| 31 <br> Side Presence Impulse Error | The control unit does not get a test answer from the activation unit. | Make sure that the monitoring output is connected and the connections are OK. |
|  |  | Replace the side presence activation unit. |
| 32 <br> Presence Impulse Error | The control unit does not get a test answer from the activation unit. | Make sure that the monitoring output is connected and the connections are OK. |
|  |  | Replace the presence activation unit. |


| Main error: E2 Emergency Unit Error |  |  |
| :---: | :---: | :---: |
| Detailed error | Reason | Remedy |
| 21 <br> Emergency Unit Error | The battery voltage drops due to low capacity during EEU test. | Charge or replace the battery. |
|  | The battery voltage measurement is wrong. | Replace the escape route unit(if present), otherwise replace the main control unit. |
| 25 <br> Battery Error | The battery is disconnected, short circuited or the internal thermal fuse in the battery is defective. The charging current is out of specification. | Make sure that the cables are OK and connected. |
|  |  | Charge or replace the battery. |
|  |  | Replace the main control unit. |
| 26 <br> Emergency Action Timeout | The door is prevented its emergency unit test within a stated time, due to high friction or jammed door. | Make sure that the door can open to the fully open position. |


| Main error: E3 Electronic Unit Error |  |  |
| :--- | :--- | :--- |
| Detailed error | Reason | Remedy |
| 00 <br> RAM Error | Internal RAM memory error. | RESET, and if the problem remains, replace the <br> electronic unit having a flashing or extinguished <br> LED. |
| 01 <br> ROM Error | Internal ROM memory error. | RESET, and if the problem remains, replace the <br> electronic unit having a flashing or extinguished <br> LED. |
| 02 <br> EEPROM Error | Serious internal EEPROM memory error. | RESET <br> Download a Default parameter set and perform a <br> RESET. If the problem remains, replace the main <br> Control unit? |


| Main error: E3 Electronic Unit Error |  |  |
| :---: | :---: | :---: |
| Detailed error | Reason | Remedy |
| 05 <br> Ambient Temperature Error | Ambient temperature measurement is wrong. | RESET, and ifthe problem remains, replace the main control unit. |
| 06 Brake Chopper Error | Not possible to activate brake chopper. | RESET, and if the problem remains, replace the main control unit. |
| 08 A/D Converter Error | The internal A/D converter is broken. | RESET, and if the problem remains, replace the electronic unit having a flashing or extinguished LED. |
| $10$ <br> Register Error | Internal register error. | RESET, and if the problem remains, replace the electronic unit having a flashing or extinguished LED. |
| $11$ | Internal program error. | RESET, and if the problem remains, replace the electronic unit having a flashing or extinguished LED. |
| 14 Lock Current Error | The lock is defective. | Check that the right lock is installed, and if the problem remains, replace the lock. |
|  |  | RESET, and if the problem remains, replace the main control unit. |
| 17 <br> Hardware Watchdog Error | It is not possible to disable the motor bridge. | RESET, and if the problem remains, replace the main control unit. |
| 18 <br> EEPROM Critical Write Error | Internal write EEPROM memory error. This error mainly occurs when it is impossible to change a configuration parameter. | RESET, and if the problem remains, replace the main control unit. |
| 22 <br> 24 V Over Current Error | The auxiliary 24 V output is overloaded. | RESET, and if the problem remains, check the connected sensors and other 24 V accessories. |
|  |  | RESET, and if the problem remains, replace the electronic unit having a flashing or extinguished LED. |
| 23 <br> Lock Circuit Error | It is not possible to disconnect the lock with the lock relay. | RESET, and if the problem remains, replace the main control unit. |
| 24 <br> Learn Error | The Learn cycle has timed out. | Make sure that the door can make a full open/close cycle. Check for high friction or jammed door and then make a new Learn. |
| 27 <br> LDB/LDE Lock Error | The LDB or LDE lock is defective. | Check that the right lock is installed; the limit switches are working and if the problem remains, replace the lock. |
| 33 <br> Flash Code Error | Serious internal programming error. | RESET, and if the problem remains, replace the main control unit. |
| 34 Output Enable Error | Test of safety related circuits failing. | RESET, and if the problem remains, replace the main control unit. |
| 35 <br> Link Voltage Error | The internal link voltage measurement is wrong. | RESET, and if the problem remains, replace the main control unit. |
| 46 <br> OMS Standard Internal Error | Internal error in the OMS Standard. | RESET, and if the problem remains, replace the OMS Standard. <br> Added in SW 5.0. |


| Main error: E4 Motor $/$ Encoder Error |  |  |
| :--- | :--- | :--- |
| Detailed error | Reason | Remedy |
| 03 <br> Encoder Error | The encoder, encoder cable, or motor cable is <br> damaged. | Make sure that the encoder cable and the motor <br> cable are connected. |
|  | Wrong motor type is selected. | Check Motor Type configuration. |
| 04 <br> Motor Current Error | The motor cable or the encoder cable is damaged. | Make sure that the encoder cable and the motor <br> cable are connected. |
|  | Wrong motor type is selected. | Check Motor Type configuration. |
| 09 <br> Encoder Cable Error | The encoder cable is damaged. | Make sure that the encoder cable is connected, <br> otherwise replace the encoder cable. |


| Main error: E5 Lock Error |  |  |
| :--- | :--- | :--- |
| Detailed error | Reason | Remedy |
| 07 <br> Lock Failure | The lock or something else was preventing the door <br> from opening the first 14 mm from closed position. | Make sure that the lock is operating without friction. <br> Make sure that Hold Force and Lock Release para- <br> meters are set correctly. |


| Main error: E6 Communication Error |  |  |
| :---: | :---: | :---: |
| Detailed error | Reason | Remedy |
| 12 <br> Motor Control Communication Error | Motor control processor disconnected from the internal bus. | RESET, and ifthe problem remains, replace the main control unit. |
| 13 <br> DoorControl Communication Error | Door control processor disconnected from the internal bus. | RESET, and ifthe problem remains, replace the main control unit. |
| 36 <br> Escape Route Communication Error | Escape route unit processor disconnected from the internal bus. | RESET, and if the problem remains, replace the escape route control unit. |
| 37 <br> I/O Communication Error | I/O control unit disconnected from the internal bus. | RESET, and if the problem remains, replace the I/O control unit. |
| 38 I/OBrand Mismatch Error | The $\mathrm{I} / \mathrm{O}$ control unit is not of the brand EM . | Replace the I/O control unit with a I/O control unit of the brand EM. <br> Added in SW 3.2. |
| 39 <br> OMS Brand Mismatch Error | The Operation mode selector (OMS) is not of the brand EM. | Replace the Operation mode selector (OMS) with a OMS of the brand EM. <br> Added in SW 3.2. |
| 47 <br> OMS Communication Error | Corrupted communication with the OMS when selecting operation mode. | RESET, and if the problems remains change the OMS If the problem still remains after changing the OMS change the MCB or MCB-ER. <br> Added in SW 5.0. |
| 51 <br> Web Communication Error | Web control unit disconnected from the internal bus. | RESET, and ifthe problem remains, replace the Web control unit. |
| 52 <br> Hi-O Communication Error | Web Hi-O unit disconnected from the internal bus. | RESET, and if the problem remains, replace the Hi O control unit. |
| 53 <br> Operation Mode Selector Communication Error | Operation mode selector(OMS) disconnected from the external bus. | RESET, check connections, and if the problem remains, replace the operation mode selector(OMS). |
| 54 <br> External Communication Error | The external bus is malfunctioning. | RESET, and if the problem remains, replace the main control unit. |
| 55 <br> CTI Brand Mismatch Error | The Configuration Tool Interface (CTI) or the MCU is not of the brand EM. | Check that the operator is a EM operator . Added in SW 3.2. |

It is not possible to replace an EM operator component with a component from a different brand.

| Main error: E7 Motor Temperature High |  | Remedy |
| :--- | :--- | :--- |
| Detailed error | Reason | The duty cycle of the door is too high for the current <br> Speed settings and Hold Open Time. |
| 16 | If the motor is warm, put the door in operation <br> mode OPEN and wait for at least 1 minute. Reduce <br> Speeds and increase Hold Open Time parameters. |  |
|  | The heavy-duty motor is replaced by a normal duty <br> motor. | Put the door in operation mode selection OPEN and <br> wait for at least 5 minutes. |


$\left.$| Main error: E8 Non-critical Error |  |  |
| :--- | :--- | :--- |
| Detailed error | Reason | Remedy |
| 49 <br> EEPROM Non-critical <br> Write Error | event log information to the EEPROM memory. |  | | RESET, and if the problem remains, replace the main |
| :--- |
| control unit if it is important to read logged inform- |
| ation. | \right\rvert\, | Too many Events to log. Reduce the number of |
| :--- |
| events to log in the Event Log configuration. |


| OMS Basic Error Codes |  |  |
| :---: | :---: | :---: |
| Detailed error | Reason | Remedy |
| Red light every 2 seconds | Error in door operator MCU. | RESET, and if the problem remains a service visit is required. See also page 121. |
| Red light 4 times per second | Internal error in the OMS Basic. | Replace the OMS Basic. |
| Steady red light | When an impulse is given on IOU TB:6 (Mode Selector Enable) the indication LED on OMS Basic will be steady red for 15 seconds. | - |

### 16.1 After remedy or replacement the operator has to be checked as follows:

a Study the door movement and adjust the functions to the values required for a smooth door operation and make sure to complete with local regulations.
b Check that correct functions and values have been selected for the installed accessories and that the installation complies with valid regulations and requirements from the authorities.
c Clean the cover and the doors.

## 17 Service/Maintenance

Regular inspections shall be made according to national regulations and product documentation by an Entrematic Nordic-trained and qualified technician. The number of service occasions should be in accordance with national requirements and product documentation. This is especially important when the installation concerns a fire-approved door or a door with an emergency opening function.

As with all other technical products, an automatic door needs maintenance and service. It is essential to know the importance of maintenance to have a reliable and safe product.

Service and adjustments will ensure a safe and proper operation of an automatic door unit.
The "Service Log Book" shall be used together with the "Site Acceptance Test and Risk Assessment" document provided. Keep both documents available for maintenance and service records.

The table below shows the recommended interval in months, when to replace parts during preventive maintenance.

| Part | Part number | Cycles/hour in operation |  |  | Abusive <br> Environment |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | $\begin{gathered} <10 \\ \hline \begin{array}{c} \text { Low } \\ \text { traffic } \end{array} \end{gathered}$ | $<100$ <br> Medium traffic | $>100$ <br> High traffic |  |
|  |  |  |  |  |  |
| Electrical emergency unit battery | 330000419 | 24 | 24 | 24 | 24 |
| Floor guide shoe Standard Felt padded Break-out | $\begin{array}{\|l} 33830064 \\ 33831622 \\ 830792 \end{array}$ | 24 | 12 | 6 | 6 |
| Door carriage <br> Plastic wheels <br> Steel wheels <br> Anti-riser device | $\begin{aligned} & 330000381 \\ & 330000382 \\ & 330000434 \end{aligned}$ | 36 | 24 | 12 | 12 |
| Sliding track | 330000466 | 36 | 36 | 36 | 24 |
| Tooth belt | 330000464 | 48 | 48 | 48 | 36 |
| Drive unit damper kit | 330000377 | 60 | 60 | 60 | 60 |
| Lock ramp | 330000661 | 60 | 60 | 60 | 60 |
| Belt clamp | 330000430 | 60 | 48 | 36 | 24 |
| Plastic protector center shaft kit | 330000393 | 60 | 60 | 60 | 48 |
| Door stop rubber kit | 330000440 | 24 | 24 | 24 | 24 |
| Tension wheel assembly | 330000447 | 36 | 36 | 36 | 36 |
| Detachment guard | 331012777 | 60 | 60 | 60 | 60 |
| Brush/sealing <br> Slim, Slim Thermo Frame, Slim, Slim Thermo | $\begin{array}{\|l\|l} 33716223 \\ 33738789 \end{array}$ | 12 | 12 | 12 | 12 |

Check that all required signage, see page 97 , is applied and intact. Also check other consumable parts, such as brushes, door stops and glazing rubbers.

### 17.1 Service

a Remove dust and dirt from the operator. Dirt on the sliding track should be removed with methylated spirits. If necessary replace the sliding track.
b None of the parts need lubrication.
c The tooth belt must be kept dry and clean. Check the belt tension.
d Check that all nuts and bolts are tightened well.
e Check the status of the door wheels, sliding track, belt, floor guides and all the other consumables, and change them if needed or if they have completed the life cycle period according to the described in chapter .
f Check the correct functionality of the Program Selector in all the different positions.
g Adjust, if necessary, the door leaf speed, the HOLD OPEN TIME and the door leaf position to comply with valid regulations and requirements.
h Check, and re-adjust if needed, door leaves height and tilt to secure a proper and smooth sliding, opening and closing.
i Check, re-adjust or exchange if needed, brushes, rubber sealings etc to secure proper closing and efficient energy saving by helping to prevent energy waste.
j Check that all the safety distances required by applicable norms to prevent accidents by crushing, shearing, drawing-in, etc. are kept and respected. Re-adjust or exchange or suggest additional protection if needed.
k Check all the safety sensors, activation units, the emergency escape functionality if applicable, and the emergency opening function under Power Failure situation. Adjust or exchange if needed to secure that all the safety works properly according to applicable norms.

I If an electromechanical lock is installed check the function as follows:

- Set the operation mode selector to EXIT. The lock shall open after an inner impulse. When the lock opens there is a clicking sound from the lock. If the operator is placed as an escape route the door should open and close without any sound from the lock. The lock shall remain unlocked.
- Set the operation mode selector to OFF. Make sure the door can not be opened by pulling the door leaf in the opening direction.
- When the operation mode selector is set back to EXIT, two clicking sounds (bi-stable) or one clicking sound (locked with power) indicate that the lock is unlocked. The door should then open and close as mentioned above.


## ENTRE/MATIC

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[^0]:    * Entrematic Nordic minimum recommended requirements. Building Codes may give different specifications.
    ** Thinner wall profiles, not less than 2 mm , must be reinforced with rivet nuts.

